Taming the Factor Zoo

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Abstract

We propose a model-selection method to systematically evaluate the contribution to asset pricing of any new factor, above and beyond what a high-dimensional set of existing factors explains. Our methodology explicitly accounts for potential model-selection mistakes, unlike the standard approaches that assume perfect variable selection, which rarely occurs in practice and produces a bias due to the omitted variables. We apply our procedure to a set of factors recently discovered in the literature. While most of these new factors are found to be redundant relative to the existing factors, several of them — such as profitability and investments — have statistically significant explanatory power beyond the hundreds of factors proposed in the past. In addition, we show that our risk price estimates and their significance are stable, whereas the model selected by simple LASSO is not.

Key words: Factors, Risk Price, Post-Selection Inference, Regularized Two-Pass Estimation, Variable Selection, Machine Learning, LASSO, Elastic Net.

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1 Introduction

The search for factors that explain the cross section of expected stock returns has produced hundreds of potential factor candidates, as noted by Cochrane (2011) and most recently by Harvey et al. (2015), McLean and Pontiff (2016), and Hou et al. (2016). A fundamental task facing the asset pricing field today is to bring more discipline to the proliferation of factors. In particular, how do we judge whether a new factor adds explanatory power for asset pricing, relative to the existing set of hundreds of factors the literature has so far produced?

This paper provides a framework for systematically evaluating the contribution of individual factors relative to the myriad of existing factors the literature has proposed, and conducting appropriate statistical inference in this high-dimensional setting. In particular, we show how to estimate and test the marginal importance of any factor $g_t$ in pricing the cross section of expected returns beyond what is explained by a high-dimensional set of potential factors $h_t$, where $g_t$ and $h_t$ could be tradable or non-tradable factors. We assume the true asset pricing model is approximately low-dimensional; however, in addition to relevant asset pricing factors, $g_t$ and $h_t$ include redundant ones that add no explanatory power to the other factors, as well as useless ones that have no explanatory power at all. Selecting the relevant factors from $h_t$ and conducting proper inference on the contribution of $g_t$ above and beyond those factors is the aim of this paper.

When $h_t$ consists of a small number of factors, testing whether $g_t$ is useful in explaining asset prices while controlling for the factors in $h_t$ is straightforward: it simply requires estimating the loadings of the stochastic discount factor on $g_t$ and $h_t$ (i.e., the price of risk of these factors), and testing whether the price of risk of $g_t$ is different from zero (see Cochrane (2009)). This exercise not only tells us whether $g_t$ is useful for pricing the cross section, but it also reveals how shocks to $g_t$ affect marginal utility, which has a direct economic interpretation.

When $h_t$ consists of potentially hundreds of factors, however, standard statistical methods to estimate and test risk prices become infeasible or result in poor estimates and invalid inference, because of the curse of dimensionality. Although variable selection techniques (e.g., least absolute shrinkage and selection operator, LASSO) can be useful in (asymptotically) selecting the all and only the variables with nonzero coefficients under certain conditions and thereby reducing the dimensionality of $h_t$, relying on this result produces very poor approximations to the finite-sample distributions of the estimators, unless appropriate econometric methods are used to explicitly account for model-selection mistakes (see Chernozhukov et al. (2015)). For example, we will show by simulation below that simply applying a model-selection tool like LASSO to a large set of factors and checking whether a particular factor $g_t$ is significant (or even just checking if it gets selected) is not a reliable way to determine whether $g_t$ is actually one of the true factors.
The methodology we propose in this paper marries these new econometric methods (in particular, the double-selection LASSO method of Belloni et al. (2014b)) with two-pass regressions such as Fama-MacBeth to specifically estimate risk prices in a high-dimensional setting and evaluate the contribution of a factor to explaining asset prices. Without relying on prior knowledge about which factors to include as controls among a large number of factors in $h_t$, our procedure selects factors that are either useful in explaining the cross section of expected returns or are useful in mitigating the omitted variable bias problem due to potential model selection mistakes. We show that including both types of factors as controls is essential to conduct reliable inference on the price of risk of $g_t$.

We apply our methodology to a large set of factors proposed in the last 30 years. We collect and construct a factor data library, containing 99 risk factors. Additionally, we create nontradable and nonlinear quadratic factors, including the squares of each of these 99 factors and their interactions with the size factor, respectively. We perform a variety of empirical exercises that illustrate the importance of accounting for model-selection mistakes when conducting inference about risk prices and assessing the significance of new factors. We start by evaluating the marginal contribution of recent factors proposed in the last five years to the large set of factors proposed before 2011. The new factors include – among others – the two new factors introduced by Fama and French (2015) and Hou et al. (2014), and the intermediary-based factors from He et al. (2016). Given that the set of potential control factors includes nearly 250 factors, one might wonder whether, in practice, any additional factor could make a significant contribution to explaining the cross section of expected returns. We show that indeed several of these new factors (e.g., profitability and investment) have significant marginal explanatory power for expected returns.

Second, we show that the results of this empirical exercise are stable across both the cross section of test assets and time periods. We randomly select 2,000 subsamples with replacement from our full sample, resampling in both the cross-sectional and time-series dimensions, and show that our estimates of risk prices and their significance are stable across subsamples. In contrast, the factors selected by simple LASSO in each subsample are not stable across subsamples. This result underscores the fact that in finite samples LASSO will generally pick some wrong factors; therefore, simple LASSO should not be used to determine whether any particular factor $g_t$ belongs to the true model. Our double-selection procedure corrects for the potential mistakes by the LASSO selection thanks to a second selection step, described in greater detail below, and produces valid inference about the factors of interest despite the mistakes that occur at the factor-selection stage.

Third, we propose a recursive exercise in which factors are tested as they are introduced against previously proposed factors. The exercise shows that our procedure would have deemed factors as redundant or spurious in most cases, while finding significance for 14 of the factors (out of 99). Over time, therefore, our procedure would have screened out many factors at the time of their introduction.
The double-selection (DS) estimation procedure we propose, that combines cross-sectional asset pricing regressions with the double-selection LASSO of Belloni et al. (2014b) (designed originally for linear treatment effect models), starts by using a two-step selection method to select “control” factors from $h_t$, and then estimates the risk price of $g_t$ from cross-sectional regressions that include $g_t$ and the selected factors from $h_t$.

As the name implies, the “double selection” of factors from $h_t$ happens in two stages; both stages are crucial to obtain correct inference on $g_t$. A first set of factors is selected from $h_t$ based on their pricing ability for the cross-section of returns. Factors that appear to contribute little to pricing assets are excluded from the set of controls. This first step – effectively an application of standard LASSO to the set of potential factors $h_t$ – has the advantage of selecting factors based on their usefulness in pricing the cross section of assets, as opposed to other commonly used selection methods (e.g., principal components) that select factors based on their ability to explain the time-series variation of returns. Using a cross-sectional approach is expected to deliver more relevant factors for asset pricing.

This first step is, however, not sufficient to ensure valid inference on $g_t$, because the LASSO selection may exclude some factors that have small risk prices in sample, but whose covariance with returns are nonetheless highly cross-sectionally correlated with exposures to $g_t$. That is, we can never be sure that LASSO has selected the correct control model. Any omission of relevant factors due to model-selection errors distorts the asymptotic distribution of the estimator for the risk price of $g_t$, leading to incorrect inference on the significance – and even the sign – of $g_t$’s risk price. This issue is a well-known problem with model-selection methods (see, for example, Leeb and Pötscher (2005)), and it has spurred a large econometrics literature on uniformly valid inference, with important consequences for asset pricing tests that we explore in this paper.

To obtain reliable asymptotic inference for $g_t$, instead, including a second stage of factor selection is crucial. The second step adds to the set of controls additional factors whose covariances with returns are highly correlated in the cross section with the covariance between returns and $g_t$. Intuitively, we want to make sure to include even factors with small in-sample risk prices, if omitting them may still induce a large omitted variable bias due to the cross-sectional correlation between their risk exposures and the risk exposures to $g_t$. It is also possible that some variables selected from the second stage are redundant or even useless, but their inclusion only leads to a moderate loss in efficiency.

After selecting the set of controls from $h_t$ (including all factors selected in either of the two selection stages), we conduct inference on $g_t$ by estimating the coefficient of a standard two-pass regression using $g_t$ and the selected small number of control factors from $h_t$. This post-selection estimation step is also useful to remove biases arising from regularization in any LASSO procedure;
see, for example, Friedman et al. (2009). We then conduct asymptotic inference on the risk price of $g_t$ using a central-limit result we derive in this paper. We show by simulation that our estimator performs well in finite samples, and substantially outperforms alternative estimators.

Finally, it is worth pointing out an alternative motivation for the methodology proposed in this paper. Theoretical asset pricing models often predict that some factors ($g_t$) should be part of the stochastic discount factor, i.e. they should enter the investors’ marginal utility. Theoretical models, however, are often very stylized, and their ability to explain the cross-section is limited. This suggests that, in reality, investors may care about other risk factors that are not explicitly predicted by the model. This creates an omitted variable problem when testing for the risk price of $g_t$: if the true stochastic discount factor contains additional factors that are not explicitly incorporated in the estimation, the estimate for the price of risk of $g_t$ will be biased. Our methodology – that estimates the price of risk of $g_t$ while taking a stand on the “omitted factors” by choosing them from the large set $h_t$ – can then be seen as a way to address this omitted factor concern when estimating risk prices. In this sense, it is related to Giglio and Xiu (2016), that show how to make inference on risk premia in the presence of omitted factors. The crucial difference between the two approaches is that Giglio and Xiu (2016) focus on the estimation of risk premia (the compensation investors require for holding the $g_t$ risk), whereas this paper makes inference on risk prices of observable factors $g_t$ (the coefficient of $g_t$ in the stochastic discount factor). Both risk prices and risk premia have important, though very distinct, economic interpretations; they have different theoretical properties, and different tools need to be used to address the omitted factor problem in the two cases. Importantly, only risk prices, addressed in this paper, can speak to the contribution of factors to explaining asset prices (see Cochrane (2009)), and therefore risk prices are the appropriate concept to refer to for disciplining the zoo of factors.

Our paper builds on several strands of the asset pricing and econometrics literature. First and most directly, the paper is related to the recent literature on the high dimensionality of cross-sectional asset pricing models. Green et al. (2016) test 94 firm characteristics through Fama-Macbeth regressions and find that 8-12 characteristics are significant independent determinants of average returns. McLean and Pontiff (2016) use an out-of-sample approach to study the post-publication bias of 97 discovered risk anomalies. Harvey et al. (2015) adopt a multiple testing framework to re-evaluate past research and suggest a new benchmark for current and future factor fishing. Following on this multiple-testing issue, Harvey and Liu (2016) provide a bootstrap technique to model selection. Recently, Freyberger et al. (2017) propose a group LASSO procedure to select characteristics and to estimate how they affect expected returns nonparametrically. Kozak et al. (2017) use model-selection techniques to approximate the SDF and the mean-variance efficient portfolio as a function of all available test portfolios, and compare sparse models based on principal components of returns.
with sparse models based on characteristics. They find that the cross-sectional explanatory power of a very sparse model based on few principal components (3-5) is higher than that of an equally-small model based on characteristics, and is instead comparable to a characteristics-based model with a larger number of factors (10-30). Consistent with these results, our empirical LASSO factor selection (that includes nontradable factors and tradable factors based on characteristics) tends to choose a few tens of factors (out of about 250).

The paper naturally builds on a large literature that has identified a variety of pricing factors, starting with the CAPM of Sharpe (1964) and Lintner (1965). Among the factors that the literature has proposed, some are based on economic theory (e.g., Breeden (1979), Chen et al. (1986), Jagannathan and Wang (1996), Lettau and Ludvigson (2001), Yogo (2006), Pastor and Stambaugh (2003a), Adrian et al. (2014), He et al. (2016)); others have been constructed using firm characteristics, such as Fama and French (1993, 2015), Carhart (1997), and Hou et al. (2014). Excellent reviews of cross-sectional asset pricing include Campbell (2000), Lewellen et al. (2010), Goyal (2012), and Nagel (2013).

We also build upon the econometrics literature devoted to the estimation and testing of asset pricing models using two-pass regressions, dating back to Jensen et al. (1972) and Fama and MacBeth (1973). Over the years, the econometric methodologies have been refined and extended; see, for example, Ferson and Harvey (1991), Shanken (1992), Jagannathan and Wang (1996), Welch (2008), and Lewellen et al. (2010). These papers, along with the majority of the literature, rely on large $T$ and fixed $n$ asymptotic analysis for statistical inference and only deal with models in which all factors are specified and observable. Bai and Zhou (2015) and Gagliardini et al. (2016) extend the inferential theory to the large $n$ and large $T$ setting, which delivers better small-sample performance when $n$ is large relative to $T$. Gagliardini et al. (2017) further propose a diagnostic criterion to detect potentially omitted factors from the residuals of an observable factor model. Connor et al. (2012) use semiparametric methods to model time variation in the risk exposures as a function of observable characteristics, again when both $n$ and $T$ are large. Giglio and Xiu (2016) rely on a similar large $n$ and large $T$ analysis, but estimate risk premia (not risk prices as in this paper) in the case in which not all relevant pricing factors are observed. Raponi et al. (2016), on the other hand, study the ex-post risk premia using large $n$ and fixed $T$ asymptotics. For a review of this literature, see Shanken (1996), Jagannathan et al. (2010), and more recently, Kan and Robotti (2012).

A crucial distinction between our paper and the aforementioned literature is that we focus on the evaluation of a new factor, which may be motivated by economic theory, rather than testing or estimating an entire reduced-form asset pricing model. In fact, we point out that assuming perfect model selection is implausible in asset pricing, so that making inference about the role of any factor just by looking at whether that factor is selected by LASSO or other model-selection techniques is
unreliable. Instead, we do not take a stand on which model is correct: we use the model selection methods to approximate a part of the stochastic discount factor that serves as control, and we explicitly account for potential model selection mistakes when conducting inference. To the extent that the procedure is used to test a new factor $g_t$ that is determined ex-ante and motivated by theory, it is not directly subject to the multiple testing concern that Harvey and Liu (2016) aim to address.1

Our procedure also helps alleviate the concern of data-snooping, another form of multiple testing (see e.g., Lo and MacKinlay (1990), Harvey et al. (2015)), because we suggest imposing discipline to the selection of controls as opposed to the conventional practice of selecting arbitrary controls that leaves the researcher much more freedom.

Of course, the existing literature has routinely attempted to evaluate the contribution of new factors relative to some benchmark model, typically by estimating and testing the alpha of a regression of the new factor onto existing factors (e.g., Barillas and Shanken (2015) and Fama and French (2016)). Our methodology differs from the existing procedures in several ways. First, we do not use as control an arbitrary set of factors from $h_t$ (e.g., the three Fama-French factors), but rather we select from $h_t$ the control model that best explains the cross section of returns. In addition, our procedure aims to minimize the potential omitted variable bias while enhancing statistical efficiency. Second, we not only test whether the factor of interest $g_t$ is useful in explaining asset prices, but we also estimate its role in driving marginal utility (its coefficient in the stochastic discount factor, or risk price); this is important to be able to interpret the results in economic terms and relate them to the models that motivated the choice of $g_t$. Third, our procedure handles both traded and non-traded factors. Fourth, our procedure leverages information from the cross section of the test assets in addition to the times-series of the factors. Lastly, our inference is valid given a large dimensional set of controls and test assets in addition to an increasing span of time series.

A recent literature has focused on various pitfalls in estimating and testing linear factor models. For instance, ignoring model misspecification and identification failure leads to an overly positive assessment of the pricing performance of spurious (Kleibergen (2009)) or even useless factors (Kan and Zhang (1999a,b); Jagannathan and Wang (1998)), and biased risk-premia estimates of true factors in the model. Therefore, the use of inference methods that are robust to model misspecification is more reliable (Shanken and Zhou (2007); Kan and Robotti (2008); Kleibergen (2009); Kan and Robotti (2009); Kan et al. (2013); Gospodinov et al. (2013); Kleibergen and Zhan (2014); Gospodinov et al. (2014); Bryzgalova (2015); Burnside (2016)). Existing literature considers the inference of pseudo-true parameters in the presence of model misspecification, whereas we correct the model misspecification bias and make inference about the original parameters.

1The two methodologies could potentially be combined to produce more conservative inference that also deals with the possibility that the set of test factors $g_t$ is selected ex-post after looking at the inference results, raising concerns about multiple testing. We leave this for future research.
Last but not least, our paper is related to a large statistical and machine-learning literature on variable selection and regularization using LASSO and post-selection inference. For theoretical properties of LASSO, see Bickel et al. (2009), Meinshausen and Yu (2009), Tibshirani (2011), Wainwright (2009), Zhang and Huang (2008), Belloni and Chernozhukov (2013). For the post-selection-inference method, see, for example, Belloni et al. (2012), Belloni et al. (2014b), and review articles by Belloni et al. (2014a) and Chernozhukov et al. (2015). Our asymptotic results are new to the existing literature in two important respects. First, our setting is a large panel regression with a large number of factors \( p \), in which both cross-sectional and time-series dimensions \( n \) and \( T \) increase. Second, our procedure in fact selects covariances between factors and returns, which are contaminated by estimation errors, rather than factors themselves that are immediately observable.

The rest of the paper is organized as follows. In Section 2, we set up the model, present our methodology, and develop relevant statistical inference. Section Appendix A provides Monte Carlo simulations that demonstrate the finite-sample performance of our estimator. In Section 3, we show several empirical applications of the procedure. Section 4 concludes. The appendix contains technical details.

2 Methodology

2.1 Model Setup

We start from a linear specification for the stochastic discount factor (SDF):

\[
m_t := \gamma_0^{-1} - \gamma_0^{-1} \lambda_g^T v_t := \gamma_0^{-1} (1 - \lambda_g^T g_t - \lambda_h^T h_t),
\]

where \( \gamma_0 \) is the zero-beta rate, \( g_t \) is a \( d \times 1 \) vector of factors to be tested, and \( h_t \) is a \( p \times 1 \) vector of potentially confounding factors. Both \( g_t \) and \( h_t \) are de-meaned; that is, they are factor innovations satisfying \( E(g_t) = 0 \) and \( E(h_t) = 0 \). \( \lambda_g \) and \( \lambda_h \) are \( d \times 1 \) and \( p \times 1 \) vectors of parameters, respectively. We refer to \( \lambda_g \) and \( \lambda_h \) as the risk prices of the factors \( g_t \) and \( h_t \).

Our goal here is to make inference on the risk prices of a small set of factors \( g_t \) while accounting for the explanatory power of a large number of existing factors, collected in \( h_t \). These factors are not necessarily all useful factors: their corresponding risk prices may be equal to zero. This framework potentially includes redundant factors (factors that have a risk price of zero but whose covariances with returns are correlated in the cross section with the covariance between returns and the SDF), as well as completely useless factors (factors that have a risk price of zero and whose covariances with returns are uncorrelated with the covariances of returns with the SDF).

We want to estimate and test the risk price of \( g_t \) for two reasons. First, it directly reveals whether \( g_t \) drives the SDF after controlling for \( h_t \), that is, whether \( g_t \) contains additional pricing
information relative to \( h_t \) (Cochrane (2009)), or whether it is instead redundant or useless. Second, the coefficient \( \lambda_g \) indicates how \( g_t \) affects marginal utility conditional on other factors in the model. For example, a positive sign for \( \lambda_g \) tells us that states where \( g_t \) is low are high-marginal-utility states. The estimate of \( \lambda_g \) can therefore be used to test predictions of asset pricing models about how investors perceive \( g_t \) shocks.

In addition to \( g_t \) and \( h_t \), we observe a \( n \times 1 \) vector of test asset returns, \( r_t \). Because of (1), expected returns satisfy:

\[
E(r_t) = \iota_n \gamma_0 + C_v \lambda_v = \iota_n \gamma_0 + C_g \lambda_g + C_h \lambda_h, \tag{2}
\]

where \( \iota_n \) is a \( n \times 1 \) vector of 1s, \( C_a = \text{Cov}(r_t, a_t) \), for \( a = g, h, \) or \( v \). Furthermore, we assume the dynamics of \( r_t \) follow a standard linear factor model:

\[
r_t = E(r_t) + \beta_g g_t + \beta_h h_t + u_t, \tag{3}
\]

where \( \beta_g \) and \( \beta_h \) are \( n \times d \) and \( n \times p \) factor-loading matrices, \( u_t \) is a \( n \times 1 \) vector of idiosyncratic components with \( E(u_t) = 0 \) and \( \text{Cov}(u_t, v_t) = 0 \).

Equation (2) represents expected returns in terms of (univariate) covariances with the factors, multiplied by risk prices \( \lambda_g \) and \( \lambda_h \). An equivalent representation of expected returns can be obtained in terms of multivariate betas:

\[
E(r_t) = \iota_n \gamma_0 + \beta_g \gamma_g + \beta_h \gamma_h, \tag{4}
\]

where \( \beta_g \) and \( \beta_h \) are the factor exposures (i.e., multivariate betas) and \( \gamma_g \) and \( \gamma_h \) are the risk premia of the factors. Risk prices \( \lambda \) and risk premia \( \gamma \) are directly related through the covariance matrix of the factors, but they differ substantially in their interpretation. In this paper, we aim to estimate the risk premium \( \gamma \) of a factor tells us whether investors are willing to pay to hedge a certain risk factor, but it does not tell us whether that factor is useful in pricing the cross section of returns. For example, a factor could command a nonzero risk premium without even appearing in the SDF, simply because it is correlated with the true factors. As discussed extensively in Cochrane (2009), to understand whether a factor is useful in pricing the cross section of assets, we should look at its risk price \( \lambda \), not its risk premium \( \gamma \).

Because the link between risk prices and risk premia depends on the covariances among factors, it is useful to write explicitly the projection of \( g_t \) on \( h_t \) as

\[
g_t = \eta h_t + z_t, \quad \text{where} \quad \text{Cov}(z_t, h_t) = 0. \tag{5}
\]

Finally, for the estimation of \( \lambda_g \), it is essential to characterize the cross-sectional dependence between \( C_g \) and \( C_h \), so we write the cross-sectional projection of \( C_g \) onto \( C_h \) as:

\[
C_g = \iota_n \xi^\top + C_h \chi^\top + C_e, \tag{6}
\]
where $\xi$ is a $d \times 1$ vector, $\chi$ is a $d \times p$ matrix, and $C_e$ is a $n \times d$ matrix of cross-sectional regression residuals.\(^2\)

### 2.2 Challenges with Standard Two-Pass Methods

Using two-pass regressions to estimate empirical asset pricing models dates back to Jensen et al. (1972) and Fama and MacBeth (1973). Partly because of its simplicity, this approach is widely used in practice. The procedure involves two steps, including one asset-by-asset time-series regression to estimate individual factor loadings $\beta$s, and one cross-sectional regression of expected returns on the estimated factor loadings to estimate risk premia $\gamma$.

Because our parameter of interest is the risk price of $g_t$, $\lambda_g$, instead of the risk premium, the first step needs to be modified to use covariances between returns and factors rather than multivariate betas. In a low-dimensional setting, this method would work smoothly for the estimation of $\lambda_g$, as pointed out by Cochrane (2009).

However, the empirical asset pricing literature has created hundreds of factors, which can include useless and redundant factors in addition to useful factors; all and only the useful ones should be used as controls in estimating the risk price of newly proposed factors $g_t$ and testing for their contribution to asset pricing ($\lambda_g$). Over time, the number of potential factors $p$ discovered in the literature has increased to the same scale as, if not greater than, $n$ or $T$. In such a scenario, the standard cross-sectional regression with all factor covariances included is at best highly inefficient. Moreover, when $p$ is larger than $n$, the standard Fama-MacBeth approach becomes infeasible because the number of parameters exceeds the sample size.

Standard methodologies therefore do not work well if at all in a high-dimensional setting due to the curse of dimensionality, so that dimension-reduction and regularization techniques are inevitable for valid inference. The existing literature has so far employed ad hoc solutions to this dimensionality problem. In particular, in testing for the contribution of a new factor, it is common to cherry-pick a handful of control factors, such as the prominent Fama-French three factors, effectively imposing an assumption that the selected model is the true one (and is not missing any additional factors). However, this assumption is clearly unrealistic. These standard models have generally poor performance in explaining a large available cross section of expected returns beyond 25 size- and value-sorted portfolios, indicating omitted factors are likely to be present in the data. The stake of selecting an incorrect model is high, because it leads to model misspecification and omitted variable bias when

\(^2\)For the sake of clarity and simplicity, we assume the set of testing assets used is not sampled randomly but deterministically, so that these covariances and loadings are treated as non-random. This is without loss of generality, because their sampling variation does not affect the first-order asymptotic inference. By contrast, Gagliardini et al. (2016) consider random loadings as a result of a random sampling scheme from a continuum of assets.
useful factors are not included, or an efficiency loss when useless or redundant factors are included.

2.3 Sparsity and LASSO

This issue is not unique to asset pricing. To address it, we need to impose a certain low-dimensional structure in the model. In this paper, we impose a sparsity assumption that has a natural economic interpretation and has recently been studied at length in the machine-learning literature. Imposing sparsity in our setting means that a relatively small number of factors exist in \( h_t \), whose linear combinations along with \( g_t \) yield the SDF \( m_t \), and those alone are relevant for the estimation of \( \lambda_g \). More specifically, sparsity in our setting means there are only \( s \) non-zero entries in \( \lambda_h \), and in each row of \( \eta \) and \( \chi \), where \( s \) is small relative to \( n \) and \( T \). The sparsity assumption allows us to extract the most influential factors, while making valid inference on the parameters of interest, without prior knowledge or even perfect recovery of the useful factors that determine \( m_t \).

Does sparsity make sense in asset pricing? In fact, the asset pricing literature has adopted the concept of sparsity without always explicitly acknowledging it. In addition to the proposed factor or the factor of interest, almost all empirical asset pricing models include only a handful of control factors, such as the Fama-French three or five factors, the momentum factor, etc. Such models provide a parsimonious representation of the cross section of expected returns, hence they typically outperform models with many factors in out-of-sample settings. This is a form of sparsity where the few factors allowed to have a non-zero risk price are chosen ex ante. Moreover, sparse models are easier to interpret and to link to economic theories, compared to alternative latent factor models, which often use the principal components as factors. Last but not least, as advocated in Friedman et al. (2009), one should “bet on sparsity” since no procedure does well in dense problems. The notion of sparse versus dense is relative to the sample size, the number of covariates, the signal to noise ratio, etc. Sparsity does not necessarily mean that the true model should always only involve a very small number of factors, say 3 or 5. More non-zero coefficients can be identified given better conditions (e.g., larger sample size), and in our empirical work we in fact find that twenty or more factors may be needed to achieve a good approximation of the SDF (still, a large reduction compared to the 300 potential factors in \( h_t \)).

To leverage sparsity, Tibshirani (1996) proposes the so-called LASSO estimator, which incorporates into the least-squares optimization a penalty function on the \( L_1 \) norm of parameters, which leads to an estimator that has many zero coefficients in the parameter vector. The LASSO estimator has appealing properties in particular for prediction purposes. With respect to parameter estimation, however, a well-documented finite-sample bias is associated with the non-zero coefficients of the LASSO estimate because of the regularization. For these reasons, Belloni and Chernozhukov (2013) and Belloni et al. (2012) suggest the use of a “Post-LASSO” estimator, which has more desirable
statistical properties. The Post-LASSO estimator runs LASSO as a model selector, and then re-fits the least-squares problem without penalty, using only variables that have non-zero coefficients in the first step.

2.4 Single-Selection LASSO and Model Selection Mistakes

In the asset pricing context, the LASSO and Post-LASSO procedures could theoretically be used to select the factors in $h_t$ with non-zero risk prices as controls for $g_t$, therefore accounting for the possibility that $h_t$ contains useless or redundant factors. In fact, when the number of factors is large, LASSO and Post-LASSO will asymptotically recover the true model under certain assumptions.

Unfortunately, these procedures are not appropriate when we conduct inference about risk prices (e.g., about the price of $g_t$ as in our context), because in any finite sample, we can never be sure LASSO or Post-LASSO will select the correct model from $h_t$, just like we cannot claim the estimated parameter values in a given finite sample are equal to their population counterparts. But if the model is misspecified, that is, if important factors from $h_t$ are mistakenly excluded, inference about risk prices will be affected by an omitted variable bias. Therefore, standard LASSO or Post-LASSO regressions will generally yield erroneous inference about risk prices, as we confirm in simulations in Appendix A.

This omitted variable bias due to model-selection mistakes is exacerbated if risk exposures to the omitted factors are highly correlated in the cross section with the exposures to $g_t$ (even though these factors may have a small in-sample price of risk, which is why they may be omitted by LASSO). We will therefore need to ensure that these factors are included in the set of controls even if LASSO would suggest excluding them. Note this issue is not unique to high-dimensional problems – see, for example, Leeb and Pötscher (2005) – but it is arguably more severe in such a scenario because model selection is inevitable.

2.5 Two-Pass Regression with Double Selection LASSO

To guard against omitted variable biases due to selection mistakes, we therefore adopt a double-selection strategy in the same spirit as what Belloni et al. (2014b) propose for estimating the treatment effect. The first selection (basically, standard LASSO) searches for factors in $h_t$ whose covariances with returns are useful for explaining the cross section of expected returns. A second selection is then added to search for factors in $h_t$ potentially missed from the first step, but that, if omitted, would induce a large omitted variable bias. Factors excluded from both stages of the double-selection procedure must have small risk prices and have covariances that correlate only mildly in the cross section with the covariance between factors of interest $g_t$ and returns – these factors can be excluded with minimal omitted variable bias. This strategy results in a parsimonious model that minimizes
the omitted factor bias ex ante when estimating and testing \( \lambda_g \).

The regularized two-pass estimation proceeds as follows:

(1) Two-Pass Variable Selection

(1.a) Run a cross-sectional LASSO regression of average returns on sample covariances between factors in \( h_t \) and returns:

\[
\min_{\gamma, \lambda} \left\{ n^{-1} \left\| \bar{r} - \eta_n \gamma - \hat{C}_h \lambda \right\|^2 + \tau n^{-1} \| \lambda \|_1 \right\},
\]

where \( \hat{C}_h = \hat{\text{Cov}}(r_t, h_t) = T^{-1} \bar{R} \bar{H} \). This step selects among the factors in \( h_t \) those that best explain the cross section of expected returns. Denote \( \{ \hat{I}_1 \} \) as the set of indices corresponding to the selected factors in this step.

(1.b) For each factor \( j \) in \( g_t \) (with \( j = 1, \cdots, d \)), run a cross-sectional LASSO regression of \( \hat{C}_{g,\cdot,j} \) (the covariance between returns and the \( j \)th factor of \( g_t \)) on \( \hat{C}_h \) (the covariance between returns and all factors \( h_t \)):

\[
\min_{\xi_j, \chi_j} \left\{ n^{-1} \left\| (\hat{C}_{g,\cdot,j} - \eta_n \xi_j - \hat{C}_h \chi_{j\cdot}) \right\|^2 + \tau_j n^{-1} \| \chi_{j\cdot} \|_1 \right\}.
\]

This step identifies factors whose exposures are highly correlated to the exposures to \( g_t \) in the cross-section. This is the crucial second step in the double-selection algorithm, that identifies factors that may be missed by the first step but that may still induce large omitted variable bias in the estimation of \( \lambda_g \) if omitted, due to their covariance properties. Denote \( \{ \hat{I}_{2,j} \} \) as the set of indices corresponding to the selected factors in the \( j \)th regression, and \( \hat{I}_2 = \bigcup_{j=1}^d \hat{I}_{2,j} \).

(2) Post-selection Estimation

Run an OLS cross-sectional regression using covariances between the selected factors from both steps and returns:

\[
(\hat{\gamma}_0, \hat{\lambda}_g, \hat{\lambda}_h) = \arg \min_{\gamma_0, \lambda_g, \lambda_h} \left\{ \left\| \bar{r} - \eta_n \gamma_0 - \hat{C}_g \lambda_g - \hat{C}_h \lambda_h \right\|^2 : \left. \lambda_{h,j} = 0, \quad \forall j \notin \hat{I} = \hat{I}_1 \cup \hat{I}_2 \right\}.
\]

We refer to this procedure as a double-selection approach, as opposed to the single-selection approach which only involves (1.a) and (2).

The LASSO estimators involve only convex optimizations, so that the implementation is quite fast. Statistical software such as R, Python, and Matlab have existing packages that implement

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3 We use \( \| A \| \) and \( \| A \|_1 \) to denote the operator norm and the L1 norm of a matrix \( A = (a_{ij}) \), that is, \( \lambda_{\text{max}}(A^TA) \), \( \max_j \sum_i |a_{ij}| \), where \( \lambda_{\text{max}}(\cdot) \) denotes the largest eigenvalue of a matrix.

4 For any matrix \( A = (a_1 : a_2 : \cdots : a_T) \), we write \( \bar{a} = T^{-1} \sum_{t=1}^T a_t, \bar{A} = A - \bar{I} \bar{\bar{a}}. \)

5 For any matrix \( A \), we use \( A_i \) and \( A_{\cdot j} \) to denote the \( i \)th row and \( j \)th column of \( A \), respectively.
LASSO using efficient algorithms. Note that other variable-selection procedures are also applicable. Either (1.a) or (1.b) can be replaced by other machine-learning methods such as regression tree, random forest, boosting, and neural network, as shown in Chernozhukov et al. (2016) for treatment-effect estimation, or by subset selection, partial least squares, and PCA regressions (or with Lasso selection on top of PCs similar to Kozak et al. (2017)).

It is useful to relate our approach to the recent model selection method by Harvey and Liu (2016). Their model selection procedure is an algorithm that resembles the forward stepwise regression in Friedman et al. (2009) (a so-called “greedy” algorithm). Their algorithm evaluates the contribution of each factor relative to a pre-selected best model through model comparison, and builds up the best model sequentially. Just like LASSO cannot deliver the true model in a finite sample with certainty, this algorithm cannot do so either, because it makes commitments to certain variables too early which prevent the algorithm from finding the best overall solution later. For example, if one of the factors in the pre-selected model is redundant relative to the factor under consideration (i.e., the latter factor is in the DGP and the former one is a noisy version of it), the latter factor could either be added or discarded depending on how noisy the former factor is. Neither scenario, however, yields a model that is closer to the truth. Note that, in any case, if this algorithm were preferred to LASSO for any reasons, we could easily substitute it in place of LASSO and still obtain correct inference, because our procedure explicitly accounts for model selection mistakes.

Our LASSO regression contains nonnegative regularization parameters, for example, \( \tau_j \) (\( j = 0, 1, \ldots, d \)), to control the level of penalty. A higher \( \tau_j \) indicates a greater penalty and hence results in a smaller model. The optimization becomes a least-squares problem if \( \tau_j = 0 \). In practice, we typically test one factor each time, so that this procedure involves two regularization parameters \( \tau_0 \) and \( \tau_1 \). To determine these parameters, we adopt the commonly used 5-fold cross-validation, BIC, and AIC; see, for example, Friedman et al. (2009). BIC tends to select a more parsimonious model than cross-validation and AIC.

We can also give different weights to \( \lambda_h \). Belloni et al. (2012) recommend a data-driven method for choosing a penalty that allows for non-Gaussian and heteroskedastic disturbances. We adopt a strategy in the spirit of Bryzgalova (2015), which assigns weights to \( \lambda_h \) proportional to the inverse of the operator norm of the univariate betas of the corresponding factor in \( h_t \). This strategy helps remove spurious factors in \( h_t \) because of a higher penalty assigned on those factors with smaller univariate betas.

### 2.6 Statistical Inference

We derive the asymptotic distribution of the estimator for \( \lambda_g \) under a jointly large \( n \) and \( T \) asymptotic design. Whereas \( d \) is fixed throughout, \( s \) and \( p \) can either be fixed or increasing. In the appendix,
we prove the following theorem:

**Theorem 1.** Under Assumptions B.1 - B.6 in Appendix B.2, if \( s^2 T^{1/2} (n^{-1} + T^{-1}) \log(n \vee p \vee T) = o(1) \), we have

\[
T^{1/2}(\hat{\lambda}_g - \lambda_g) \overset{\mathcal{L}}{\rightarrow} N_d(0, \Pi),
\]

where the asymptotic variance is given by

\[
\Pi = \lim_{T \to \infty} \frac{1}{T} \sum_{t=1}^{T} \sum_{s=1}^{T} \mathbb{E}\left( (1 - \hat{\lambda}^\top v_t)(1 - \hat{\lambda}^\top v_s) \Sigma_z^{-1} z_t z_s \Sigma_z^{-1} \right), \quad \Sigma_z = \text{Var}(z_t).
\]

We stress this result holds even with imperfect model selection. That is, the selected models from (7) and (8) may omit certain useful factors and include redundant ones, which nonetheless has a negligible effect on the inference of \( \lambda_g \). Using analysis similar to Belloni et al. (2014b), the results can be strengthened to hold uniformly over a sequence of data-generating processes that may vary with the sample size and only under approximately sparse conditions, so that our inference is valid without relying on perfect recovery of the correct model in finite sample. Moreover, the asymptotic distribution of \( \hat{\lambda}_g \) does not rely on covariances or factor loadings of \( g_t \) and \( h_t \), because they appear in strictly higher-order terms, which further facilitates our inference. The next theorem provides a Newey-West-type estimator of the asymptotic variance \( \Pi \).

**Theorem 2.** Suppose the same assumptions as in Theorem 1 hold. In addition, Assumption B.7 holds. If \( q_s s^{3/2} (T^{-1/2} + n^{-1/2}) \| V \|_{\max} \| Z \|_{\max} = o_p(1) \), \(^6\) we have

\[
\hat{\Pi} \overset{p}{\rightarrow} \Pi,
\]

where \( \hat{\lambda} = (\hat{\lambda}_g : \hat{\lambda}_h) \) is given by (9), and

\[
\hat{\Pi} = \frac{1}{T} \sum_{t=1}^{T} (1 - \hat{\lambda}^\top v_t)^2 \hat{\Sigma}_z^{-1} \hat{z}_t \hat{z}_t^\top \hat{\Sigma}_z^{-1}
\]

\[
+ \frac{1}{T} \sum_{k=1}^{q} \sum_{t=k+1}^{T} \left( 1 - \frac{k}{q + 1} \right) \left( (1 - \hat{\lambda}^\top v_t)(1 - \hat{\lambda}^\top v_{t-k}) \hat{\Sigma}_z^{-1} (\hat{z}_t \hat{z}_{t-k}^\top + \hat{z}_{t-k} \hat{z}_t^\top) \hat{\Sigma}_z^{-1} \right),
\]

\[
\hat{\Sigma}_z = \frac{1}{T} \sum_{t=1}^{T} \hat{z}_t \hat{z}_t^\top, \quad \hat{z}_t = g_t - \tilde{\eta}_I h_t, \quad \tilde{\eta}_I = \arg\min_{\eta} \left\{ \| G - \eta H \|^2 : \eta_{j} = 0, \quad j \notin \hat{I} \right\},
\]

and \( \hat{I} \) is the union of selected variables using a LASSO regression of each factor in \( g_t \) on \( h_t \):

\[
\min_{\eta_j} \left\{ T^{-1} \| G_{\cdot j} - \eta_j H \|^2 + \bar{\tau} T^{-1} \| \eta_j \|_1 \right\}, \quad j = 1, 2, \ldots, d.
\]

\(^6\) We use \( \| A \|_{\max} \) to denote the \( L_{\infty} \)-norm of \( A \) in the vector space.
3 Empirical Analysis

In this section we apply our methodology to our data library of hundreds of factors. We start by showing how our estimation procedure can be used to evaluate whether a newly proposed factor provides useful pricing information compared to the myriad of existing factors. We document that indeed some of the recently proposed factors (e.g., profitability and investment) contribute significantly to explaining asset prices, even controlling for a large number of existing factors in the literature. At the same time, many factors introduced in the last few years appear entirely redundant and contain no new useful information for pricing the cross section of returns.

Next, we compare our procedure to standard model selection methods for the purpose of understanding whether specific factors are useful. We show that models selected by LASSO (like other statistical selection methods) are not stable in finite samples: they vary greatly with the sample in which the estimation is performed and with the choice of tuning parameters. In other words, statistical model selection is prone to making mistakes in choosing factors in finite samples, and cannot be relied upon to make stable inference about the identities of the factors in a model. On the contrary, our testing procedure (that makes use of LASSO but explicitly accounts for model selection mistakes) produces inference that is substantially more robust.

We then perform a recursive evaluation exercise, in which we test the factors in the library as they were historically introduced in the literature, relative to the ones existing at the time; we show that had our estimator been used over time to evaluate the new factors over the last 20 years, most of the factors in our data library would have been deemed useless or redundant right when they were introduced, thus bringing discipline to the zoo of factors.

3.1 Data

3.1.1 The Zoo of Factors

Our factor library contains 99 risk factors at the monthly frequency for the period from July 1980 to December 2016, obtained from multiple sources. First, we download all workhorse factors in the U.S. equity market from Ken French’s data library. Then we add several published factors directly from the authors’ websites, including liquidity from Pástor and Stambaugh (2003a), the q-factors from Hou et al. (2014),7 and the intermediary asset pricing factors from He et al. (2016). We also include factors from the AQR data library, such as Betting-Against-Beta, HML Devil, and Quality-Minus-Junk. In addition to these 17 publicly available factors, we follow Fama and French (1993) to construct value-weighted portfolios and 82 long-short factors using those firm characteristics surveyed

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7We are grateful to Lu Zhang for sharing the updated factors data.
More specifically, we include only stocks for companies listed on the NYSE, AMEX, or NASDAQ that have a CRSP share code of 10 or 11. Moreover, we exclude financial firms and firms with negative book equity. For each characteristic, we sort stocks using NYSE breakpoints based on their previous year-end values, then build and rebalance a long-short value-weighted portfolio (top 30% - bottom 30% or 1-0 dummy difference) every June for a 12-month holding period. Both Fama and French (2008) and Hou et al. (2016) have discussed the importance of using NYSE breakpoints and value-weighted portfolios. Microcaps, i.e., stocks with market equity smaller than the 20th percentile, have the largest cross-sectional dispersion in most anomalies, while accounting for only 3% of the total market equity. Equal-weighted returns overweight microcaps, despite their small economic importance.

In Table 4 of the Appendix, we report a complete list of the 99 factors and various descriptive statistics (publication year, monthly average returns for tradable factors, and annualized Sharpe ratios), as well as the academic references. We follow Hou et al. (2014) and provide six main categories for the factor classification: Momentum, Value-versus-Growth, Investment, Profitability, Intangibles, and Trading Frictions. In our factor zoo, each category contains at least seven factors. Furthermore, to capture the potential nonlinearity of the SDF (and consistent with empirical evidence, e.g., Freyberger et al. (2017) and Kozak et al. (2017)) we add as controls 197 factors that include 99 squared terms for these primary risk factors, and 98 interaction terms between Small Minus Big and each other factor.

3.1.2 Test Portfolios

We conduct our empirical analysis on a large set of standard portfolios of U.S. equities. We target U.S. equities because of their better data quality and because they are available for a long period; however, our methodology could be applied to any set of countries or asset classes. We focus on portfolios rather than individual assets because characteristic-sorted portfolios have more stable betas, higher signal-to-noise ratios, and they are less prone to missing data issues, despite the existence of a bias-variance trade-off between the choice of portfolios and individual assets. Selecting a few portfolios based on sorts of a handful characteristics is likely to tilt the results in favor of these factors, see Harvey and Liu (2016), which is something we specifically address in our robustness tests. There might also be a loss in efficiency in using a few such portfolios, e.g., Litzenberger and Ramaswamy (1979). In line with the suggestion of Lewellen et al. (2010), we base our analysis on a large cross section of characteristic-sorted portfolios, which helps strike a balance between having many individual stocks or a handful of portfolios.

We are grateful to Jeremiah Green for sharing the firm-characteristics SAS calculation code.
We use a total of 1,825 portfolios as test assets. We start from a standard set of 175 portfolios: 25 portfolios sorted by size and book-to-market ratio, 25 portfolios sorted by size and beta, 25 portfolios sorted by size and operating profitability, 25 portfolios sorted by size and investment, 25 portfolios sorted by size and short-term reversal on prior (1-1) return, 25 portfolios sorted by size and momentum on prior (2-12) return, and 25 portfolios sorted by size and long-term reversal on prior (13-60) return. This set of test assets – all available from Kenneth French’s website – captures a vast cross-section of anomalies and exposures to different factors.9

We add to these 175 portfolios 1,650 additional ones obtained from our factor zoo, that cover additional characteristics. In particular, we include sets of 5×5 bivariate-sorted portfolios from all continuous factors in our factor zoo. The sorting procedure is same as that for the construction of factors, except that the stock universe is divided into five groups for each characteristic. For each firm characteristic, the bivariate-sorted 5×5 portfolios are constructed by intersecting its five groups with those formed on size (market equity). Notice that, the number of stocks in each 5×5 group can be unbalanced in the bivariate intersection. We only include the resulting portfolios if each of the 25 groups contains a sufficient number of stocks (at least 5). This procedure gives us 66 sets of 25 bivariate-sorted portfolios, yielding 1,650 portfolios.10

As a robustness check, we have also created multiple sets of sequential-sorted portfolios using size and the other characteristics. The portfolios, which are also constructed at the end of each June, are created by first allocating stocks to five size groups. Stocks in each size group are then assigned to five sub-groups for the other characteristics using quantile breakpoints specific to that size group. This sorting gives 70 sets of 5×5 sequential-sorted portfolios, because we now have portfolios associated with 5 characteristics (8, 43, 44, 48, and 41) that have large correlations with size, but lose portfolios for Industry Momentum (37) (one of its 25 portfolio groups has less than 5 stocks.). A main advantage for the sequential-sorted portfolios is the numbers of stocks are more balanced in each 5×5 group than the bivariate-sorted portfolios.

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9See the description of all portfolio construction on Kenneth French’s website: [http://mba.tuck.dartmouth.edu/pages/faculty/ken.french/data_library.html](http://mba.tuck.dartmouth.edu/pages/faculty/ken.french/data_library.html).

10There are 16 factors for which bivariate-sorted portfolios are not available. 9 of 16 are dummy or categorical characteristics, including Dividend Initiation (25), Dividend Omission (26), New Equity Issue (27), Financial Statements Score (42), Number of earnings increases (38), # Years Since First Compustat Coverage (57), Financial Statement Performance (60), Sin Stocks (78), and Convertible Debt Indicator (99). 2 of 16, including Dividend to Price (4), and R&D Increase (54) have more than one fifth of characteristic values being zero for many years. The remaining 5 of 16, including Industry-Adjusted Size (41), Bid-Ask Spread (8), Dollar Trading Volume (43), Volatility for Dollar Trading Volume (44), and Illiquidity (48), have either large positive (41) or large negative correlations (8, 43, 44, 48) with size (e.g., small firms are rarely liquid stocks), so that part of their 25 portfolios are missing.
3.2 Are New Factors Useful?

In this section we apply our methodology to factors that have been proposed in the last five years (since 2011), drawing the “control” factors from the set of more than 80 factors that were proposed before 2011, as well as the squares of these factors and interactions between the factors and size, for a total of 248 control factors (note that squares and interactions are nontradable factors).\(^{11}\) We therefore ask whether the recently introduced factors add any new pricing information to the existing tradable and nontradable factors, or are redundant or outright useless in pricing the panel of returns. We have no ex-ante reason to expect the results to go in either direction. On the one hand, given that the set of potential control factors is already extremely large, one might think that new factors are unlikely to contribute much to pricing the cross section of returns. On the other hand, we expect new research to potentially uncover better factors over time, yielding factors that improve over the existing ones.

Table 1 reports the results for the factors proposed in the last five years, among which we find Quality-Minus-Junk (QMJ), Betting-Against-Beta (BAB), two investment factors (CMA from Fama-French and IA from HXZ), two profitability factors (RMW from Fama-French and ROE from HXZ), the nontradable intermediary capital factor from He et al. (2016), and several factors constructed on accounting measures.

For each factor, we estimate its price of risk and test its significance. The estimated risk price is directly informative about how that factor enters the stochastic discount factor, that is, how investors’ marginal utility depends on that factor. This has implications for asset pricing theories, that typically predict whether a factor increases or decreases investor’s marginal utility. At the same time, a non-zero price of risk indicates that the factor is useful in explaining the cross-section of expected returns (the equivalence is discussed in detail in Cochrane (2009)).

The table contains five columns of results, each reporting the point estimate of the risk price and the corresponding t-statistic. More specifically, the point estimate corresponds to the estimated slope of the cross-sectional regression of returns on (univariate) betas for each factor, using different methodologies to select the control factors: it represents the estimated average excess return in basis points per month of a portfolio with unit \textit{univariate} beta with respect to that factor. This number is equal to the risk price \(\lambda_g\) but scaled to correspond to a unit beta exposure for ease of interpretation. A positive estimate for the risk price indicates that high values of the factor capture states of low marginal utility (good states of the world). The t-statistic in each column corresponds to the test of the hypothesis that the slope is equal to zero, constructed using different methodologies across

\(^{11}\) More precisely, we have 83 factors introduced up to 2010, 83 squared terms, and 82 interactions with size (size is one of the 83 factors).
The first column reports our main result – the estimates of risk prices for the factors introduced since 2011, with corresponding t-statistics, obtained with our double-selection (DS) procedure. Most of the new factors appear statistically insignificant – our test therefore deems them redundant or useless relative to the factors introduced up to 2011. However, we still find a few important factors useful in explaining the cross-section, as their estimated risk price is significantly different from zero: in particular, QMJ, profitability (both the version of HXZ and that of Fama and French), and investment (both the HXZ and Fama-French versions). The estimated risk prices indicate that states of high marginal utility correspond to low values for all these factors. These results show that our double-selection method can discriminate between useful and redundant factors even when the set of controls contains hundreds of factors.

The second set of results reports the estimates that one would obtain using the naive single-selection (SS) methodology – that is, simply using LASSO to select the factors to use as controls, without the second selection step that is useful to avoid the omitted variable bias due to mistakes in model selection. The results are quite different from the double-selection approach, with different factors (maximum return and organizational capital) appearing significant; none of the factors that appear significant with the DS method do so when using SS. Given our discussion in the previous sections, it should not be surprising that results obtained using the SS method differ from those obtained using the DS method: our theoretical results and simulations show that the SS method is biased in finite samples. This table shows that these biases play a major role empirically.

The third column shows instead what the risk price estimates for the various factors would be if one simply used the Fama-French 3 factors (Market, SMB, HML) as controls, rather than selecting the controls optimally among the myriad of potential factors. The results differ noticeably from the benchmark with double selection. Of course, if the true SDF was known ex ante, selecting all and only the true factors as controls would lead to the most efficient estimate for the price of risk of $g_t$. In practice, however, it is unlikely that we can pin down the entire SDF with certainty. The aim of our double-selection procedure is precisely to select the controls statistically – avoiding arbitrary choices of control factors – while at the same time minimizing the potential omitted variable bias.

The fourth column shows one more alternative way to compute risk prices: using standard OLS estimation including in the cross-sectional regression all the hundreds of potential controls. This panel therefore shows what happens if no selection is applied at all on the factors. As discussed in the previous sections, this approach is unbiased but inefficient. We expect therefore (and confirm in the table) that the results appear much more noisy and the estimates less significant than when operating dimension reduction through our DS method. This result highlights the importance of

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12Here and in the rest of the analysis we choose tuning parameters using 5-fold cross-validation.
dimension reduction methods when sorting through the myriad of existing factors.

The last column of the table shows the average excess return of the tradable factors, that is, their risk premium. This number represents the compensation investors obtain from bearing exposure to that factor, holding exposures to all other risk factors constant. As discussed, for example, in Cochrane (2009), the risk premium of a factor does not correspond to its ability to price other assets, that is, its coefficient in the SDF. Using the risk premium to assess the importance of a factor in a pricing model would be misleading. For example, consider two factors that are both equally exposed to the same underlying risk, plus some noise. Both factors will command an identical risk premium. Yet those factors are not both useful to price other assets—regardless of their level of statistical significance. The most promising way to reduce the proliferation of factors is not to look at their risk premium (no matter how significant it is), but to evaluate whether they add any pricing information to the existing factors. Our paper proposes a way to make this feasible even in a context of high dimensionality, when the set of potential control factors is large. We come back to this point in Section 3.5.¹³

To sum up, Table 1 shows that which factors are chosen as controls, and which econometric procedure is used for estimation, make a large difference for the conclusions about the risk price and the usefulness of factors. Both the theoretical analysis and the simulations provided in this paper suggest that the DS method allows researchers to make full use of the information in the existing zoo of factors without introducing biases while accounting for efficiency losses.

### 3.3 Economic Interpretation and Model Selection

The core idea of this paper is that we can make inference about the risk price and importance of a specific factor $g_t$ – motivated by economic theory – even if we do not know exactly what the other true factors are, and even if we can never be sure to have recovered the correct model via statistical model selection methods. Therefore, the exact identity of the factors selected as controls by LASSO is not of primary importance for our analysis. For completeness, we report here the list of the 14 factors (out of 248) selected from $h_t$ as controls: Excess Market Return, Sales to Inventory, Sales to Receivables, High Minus Low, Short-Term Reversal, Momentum, Industry-Adjusted Book to Market, Growth in Long Term Net Operating Assets, Change in 6-month Momentum, Change in Capital Expenditures, Return on Invested Capital, Accrual Volatility, (Cash Flow to Debt)$^2$, (Change in Shares Outstanding)$^2$.

¹³It is interesting to note that about half of these factors do not have a significant risk premium, while they typically did in the original publications. This is partly due to the different sample period used here, and partly because we use a unified sorting methodology in this paper, rather than the heterogeneous methods used in the original papers. This result is consistent with the findings of Hou et al. (2016).
To the 14 factors selected in the first stage and reported, our double-selection procedure adds additional control factors in the second stage; these additional controls are those whose risk exposures are cross-sectionally correlated with those of the target factor $g_t$, and are crucial to minimize the omitted variable bias in risk prices, as demonstrated in the theory and simulation sections. Due to space constraints, we do not report the additional factors for all the $g_t$ of Table 1: each factor $g_t$ induces a different second-stage selection (whereas the first selection of controls, the set reported above, is common to all target factors).

It is important to remark that the list of factors selected from $h_t$ by LASSO does not have (nor does it need to have) a direct economic interpretation. The objective of machine learning and model selection techniques is to reduce the dimensionality and maximize explanatory power of the low-dimensional model – not to provide an economically motivated selection of factors.

In many economic applications, the inability to interpret economically the selected model is an important shortcoming. In this paper, however, we only use model selection techniques to select the controls for the cross-sectional regression: that is, to approximate that part of the SDF that is unknown to the researcher, while recovering the true coefficient of the SDF on $g_t$. The factor of interest $g_t$ therefore retains its economic interpretation (under the theory from which it was derived), and so do the sign and magnitude of its estimated risk price: the estimated coefficient $\lambda_g$ directly tells us how that factor affects investors’ marginal utility, holding all the other factors in the SDF constant. We thus aim to combine the strength of machine learning methods with the interpretability obtained from economic theory that motivates the choice of the target factors $g_t$.

### 3.4 Stable Inference v.s. Unstable Model Selection

Statistical model selection methods not only make it hard to give an economic interpretation to the selected models; they are also prone to mistakes in selecting the factors, and the resulting models can be unstable with respect to the particular sample used and choice of tuning parameters. In this section, we show empirically that instead – as predicted by the theory of Section 2 – our double-selection inference is remarkably stable, and it is so despite the instability of the statistical model selection steps used to choose the controls from $h_t$.

We start by exploring how the model selected by LASSO (from $h_t$) and the inference about target factors $g_t$ using our double-selection method depend on the tuning parameters. Recall that each dimension-reduction step via LASSO depends on one tuning parameter. Our double-selection procedure uses LASSO in two separate steps, so two tuning parameters are needed. To produce our benchmark estimates in Table 1, we choose tuning parameters using a cross-validation criterion. Here we show that the inference about $\lambda_g$ is robust to changes in both tuning parameters, even as the set of factors selected from $h_t$ by LASSO varies dramatically.
For each of the factors \( g_t \) introduced since 2011, we compute its double-selection t-statistic and the number of factors selected by the two LASSO steps from \( h_t \), for a wide range of values of both tuning parameters. We then report them in Figure 1 using heatmaps. In the figure, each row corresponds to a different factor \( g_t \). The left panel reports t-statistics, and the right panel reports the number of control factors selected from \( h_t \). The two axes correspond to values for the two tuning parameters (in logs).

From the right panel, it is evident that our range of tuning parameters corresponds to a wide range of possible model dimensions. Consider for example the case of HXZ Profitability. Depending on the tuning parameter, the control model has anywhere between 10 and 60 factors: the factors selected by LASSO therefore vary considerably as a function of the tuning parameters; this is one way to see the instability of statistical model selection.

The left panels, however, show very high consistency in the inference about the economically-motivated factors \( g_t \), for the entire range of tuning parameters. For example, for the HXZ Profitability factor, the t-statistic is always in the range of 2 to 4, whereas for insignificant factors like employee growth, the t-statistics are below significance levels across the entire range.

Overall, Figure 1 shows that the DS procedure makes inference robust to changes in the tuning parameters, even when the LASSO-selected model is instead quite sensitive to these changes.

Next, we explore the difference between the DS inference and LASSO across subsamples of our data. In this exercise, we bootstrap our data over different time periods and test assets (with replacement on both dimensions), and perform our analysis on each bootstrap sample. For each sample, we select the control model using LASSO (re-estimating the tuning parameters in that sample only), then add factors from the second selection, and finally estimate the risk price of each target factor in that sample using our DS procedure. We construct in this way 2,000 bootstrap samples.

Figure 2 shows the distribution of t-statistics using our double-selection method for the factors introduced since 2011, across the 2,000 bootstrap samples. Recall that most of the factors in Table 1 are not significant: for those factors, we would then expect the t-statistic to be centered around 0 and the distribution of the t-statistic to lie mostly in the \((-2, +2)\) interval. Instead, we would expect factors that appear significant in our DS test to have a consistently positive (or negative) t-statistic: if the estimate of the risk price is stable across different samples, we would expect the distribution to lie mostly on one side of 0 (the side of course would depend on whether the risk price is positive or negative).

The figure shows that this is indeed the case. For the factors that do not appear significant in Table 1, the distribution of t-statistics across samples is centered around zero. For the factors that
appear to be significant in Table 1 (for example, investment, profitability and QMJ) the distribution is well shifted to the right.

These results indicate that our risk price estimator gives very consistent results across samples. This is true even when the first model-selection step (based on standard LASSO) instead displays high variability across subsamples: Figure 3 shows, for each factor identified by its ID, in how many of the 2,000 samples the factor is actually selected as part of the model by simple LASSO. The figure shows striking variability in the model selection step. None of the 248 factors, except for the Market (No. 1) and Sales to Inventory (No. 16) are actually selected in more than 70% of the samples, and most of the factors are selected in 5% to 30% of the subsamples, but not in the others.

If LASSO had been able to perfectly select the true model, we should have found a small number of factors (say, 5 or 10) to be selected 100% of the time, and the remaining factors to be selected 0% of the time. Instead, LASSO clearly has difficulty pinning down which factors are the correct ones, selecting sometimes a group of them, other times a different group.

This exercise should caution us against using LASSO to decide whether a factor should be included in the SDF or not. A naive approach to deciding whether a new factor is useful in explaining the cross-section of asset prices above and beyond the existing factors would be to simply run a LASSO model selection procedure on the set of all factors (old and new), and check whether the new factor gets selected. But this approach does not lead to proper inference: the LASSO estimates will make mistakes in selecting the model, and this simple rule of thumb does not appropriately take the possibility of model selection mistakes into account. On the contrary, our double-selection procedure corrects for these mistakes, producing an unbiased and efficient estimator of $\lambda_g$ and correct inference.

3.5 Evaluating Factors Recursively: Risk Premia, Risk Prices, and t-Statistics thresholds

One of the motivations for using our methodology is that it can help distinguish useful from useless and redundant factors as they are introduced in the literature. Over time, this should help limit the proliferation of factors, and retain only those new factors that actually contain novel information to price the cross-section.

To illustrate this point, in each year starting in 1994 we consider the factors introduced during that year, and use our double-selection procedure to test whether they are useful or redundant relative to factors existing up to then. Note that the exercise is fully recursive, using only information available up to time $t$ when evaluating a factor introduced at time $t$, both in choosing the set of potential controls $h_t$ and in constructing the test portfolios (which are therefore sorted on characteristics introduced in the literature up to time $t$).
Table 2 reports the results. In the table, the factors introduced since 1994 are identified by their ID; the table underlines the ones that appear to be statistically significant according to our test, relative to the factors introduced before them. The table also reports the number of test assets used in each year and the number of control factors (that include squares and interactions) in $h_t$.

The results show that had our DS test been applied year by year starting in 1994, only 14 factors would have been considered useful, and a large majority would have been identified as redundant or useless.

It is useful to think about this exercise in light of the recent literature (e.g., McLean and Pontiff (2016), Harvey et al. (2015)) that has highlighted and tried to address the existence of a multitude of seemingly significant anomalies. The literature has proposed a variety of approaches, including adopting a stricter requirement for significance (such as using a threshold for the t-statistic of 3). Although the overarching theme is to tame the factor zoo, the perspectives are slightly different. The aforementioned papers emphasize the bias of data-snooping or raise the concern of multiple testing, whereas our focus is on omitted controls. All these problems could contribute to the proliferation of factors.

Our approach differs from the proposals in the existing literature in four substantial ways. First, and most important, we explicitly address the problem of omitted variable bias due to potential model selection mistakes when making inference about factors’ contribution to asset prices. Second, our method directly takes into account the correlation among factors, rather than considering factors individually and using Bonferroni-type bounds to assess their joint significance. We provide a statistical test of a factor’s contribution with desirable asymptotic properties, as demonstrated in the previous sections, and do not rely on simulation or bootstrap methods whose statistical properties in this context are unknown. Third, our method is specifically designed to handle hundreds of factors as controls, exploiting model-selection econometric advances to reduce the dimensionality of the factor set. Fourth, the criterion we employ for selecting factors is based on the risk price, not the risk premium of the factors (see a more detailed discussion on their differences in Section 3.2), as it it is the right quantity to evaluate the contribution of a factor to explaining asset prices.

The various approaches that have been proposed in the literature so far address complementary issues to be overcome on the path to disciplining the zoo of factor. We leave for future research refinements of these methods that can potentially combine insights from our work and other recent papers.
3.6 Robustness Checks

In this section we further explore the robustness of our results, with respect to the test assets used for the estimation, the set of potential control factors \( h_t \), and the dimension-reduction methodology used to select the control factors. We focus our robustness tests on the evaluation of recent factors (Table 1).

Column (1) of Table 3 reports our baseline results for convenience (as in the first column of Table 1). In column (2) we show results that use a sequential-sorting procedure to construct the \( 5 \times 5 \) characteristic-sorted portfolios so as to demonstrate robustness to missing data. The results are consistent with our baseline specification, except that one more factor becomes significant.

Next, in column (3) we consider using only test portfolios constructed from characteristics available before 1994 when estimating the risk prices of all factors. The goal of this test is to highlight the fact that our results do not depend on including, among the test assets, portfolios sorted on the same characteristics on which the factors themselves were built. While the number of available test portfolios is smaller in this case, i.e., 450, the factors that appear significant are the same as in the baseline case.

We then conduct a robustness test on the set of potential control factors \( h_t \). In column (4), we repeat our analysis including only tradable factors in the set of controls (that is, excluding factors that are nontradable as well as interactions and squared factors). Again, the results are consistent with our benchmark.

Finally, the last column shows that our results hold also when using a different dimension-reduction procedure. Which method is preferred in each context depends on the underlying model assumptions, and given the assumptions we make, LASSO would be the most suitable model-selection method. However, Elastic Net is a reasonable alternative to explore in this context: it combines a penalty from LASSO with that of the Ridge regression. The model selected by the Elastic Net is naturally larger, but, as column (5) in the table shows, the results are consistent with our benchmark based on pure LASSO.

Overall, while across the different robustness tests the significance of some factors changes slightly, the main conclusions of Table 1 appear quite robust to these changes in specification. The table confirms that several of the factors introduced recently (like investment, profitability, and QMJ) have significant additional pricing power relative to all factors introduced in the literature before 2011.
4 Conclusion

In this paper we propose a regularized two-pass cross-sectional regression approach to establish the contribution to asset pricing of a factor $g_t$ relative to a set of control factors $h_t$, where the potential control set can have high dimensionality and include useless or redundant factors. Our procedure uses recent model-selection econometric techniques (specifically the double-selection procedure of Belloni et al. (2014b)) to systematically select the best control model out of the large set of factors, while explicitly taking into account that in any finite sample we cannot be sure to have selected the correct model.

We apply this methodology to a large set of factors that the literature has proposed in the last 30 years. We uncover several interesting empirical findings. First, several newly proposed factors (for example, investment, profitability and QMJ) are useful in explaining asset prices, even after accounting for the large set of existing factors proposed up to 2011. Second, the risk price estimates (and the evaluation of the usefulness of factors) that we obtain are stable across different samples, whereas the models selected vary substantially when the data is resampled. Third, applying our test recursively over time would have deemed only a small number of factors proposed in the literature significant. Lastly, we demonstrate how our results differ starkly from the conclusions one would obtain simply by using the risk premia of the factors or the standard Fama-French three factor model as control (as opposed to the model selection procedure we advocate).

Taken together, our results are quite encouraging about the continuing progress of asset pricing research, and suggest that studying the marginal contribution of new factors relative to the vast set of existing ones is a conservative and productive way to screen new factors as they are proposed, as well as to organize the current “zoo of factors.”
References


Table 1: Testing for Factors Introduced in 2011-2016

<table>
<thead>
<tr>
<th>id</th>
<th>Factor Description</th>
<th>(1)</th>
<th>(2)</th>
<th>(3)</th>
<th>(4)</th>
<th>(5)</th>
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<td></td>
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<td>$\lambda_s$</td>
<td>tstat</td>
<td>$\lambda_s$</td>
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<td>-2.93***</td>
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<td>CMA</td>
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</table>

Note. The table reports tests for the contribution of factors introduced in 2011-2016 relative to the set of factors introduced up to 2010. The set of 248 potential controls includes the factors introduced up to and including 2010, their squares and interactions with size. For each column, we show the estimate of risk price $\lambda_g$ and the t-statistic. The first column uses the double-selection (DS) method, our benchmark. The regularization parameters in each selection are chosen by 5-fold cross-validation. The second column uses the single-selection (SS) method. The third column uses the Fama-French 3 factors as controls. The fourth column estimates risk prices using all factors as controls, without using dimension-reduction techniques, with simple OLS. The last column reports the risk premium of each tradable factor. Sample period is from July 1980 to December 2016.
Table 2: Testing Factors Recursively by Year of Publication

<table>
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<th>Year</th>
<th># Assets</th>
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<th>New factors (IDs)</th>
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<td>550</td>
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<tr>
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<td>89</td>
<td>31, 32, 33, 34, 35, 36</td>
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<td>1999</td>
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<tr>
<td>2000</td>
<td>750</td>
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<td>825</td>
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<td>46, 47, 48</td>
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<tr>
<td>2003</td>
<td>875</td>
<td>143</td>
<td>49, 50, 51</td>
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<tr>
<td>2004</td>
<td>925</td>
<td>152</td>
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<tr>
<td>2005</td>
<td>1025</td>
<td>167</td>
<td>57, 58, 59, 60, 61</td>
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<td>2016</td>
<td>1825</td>
<td>287</td>
<td>97, 98, 99</td>
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Note. The table reports the results of a recursive factor-testing exercise, from 1994 to 2016. For each year t, column (1) reports the number of test assets available for the test at that point in time, sorted on characteristics available up to then. Column (2) reports the number of controls available in each year t, i.e. the number of potential controls in \( h_t \) based on factors introduced up to then, plus their squares and interactions with size. Column (3) shows for each year the IDs of the factors that were introduced during that year. We then test whether each new factor contributes to explaining asset prices relative to the factors published in previous years, using only the data available up to time t. We underline the IDs in column (3) every time the factor appears significant using our double-selection test. The regularization parameters in each selection are chosen by 5-fold cross-validation.
Table 3: Robustness for Factors Introduced in 2011-2016

<table>
<thead>
<tr>
<th>id</th>
<th>Factor Description</th>
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<th>(4) (bp)</th>
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<td>(DS)</td>
<td>(DS)</td>
<td>(DS)</td>
<td>(DS)</td>
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<tr>
<td>84</td>
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<td>Percent Accruals</td>
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<tr>
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<td>87</td>
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<td>107 2.60***</td>
<td>193 4.51***</td>
<td>31 0.81</td>
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<td>92</td>
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<td>41 1.93*</td>
<td>48 2.28**</td>
<td>64 2.83***</td>
<td>48 2.10**</td>
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<td>Employee Growth</td>
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<td>-11 -0.31</td>
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<td>95</td>
<td>RMW</td>
<td>122 4.66***</td>
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</table>

**Note.** The table reports robustness tests for the estimates of risk prices for factors introduced in 2011-2016 relative to the set of factors introduced up to 2010. The first column shows the same results as in the first column of Table 1 for convenience. The second column shows the results using sequentially-sorted portfolios, the third column uses only characteristics-sorted portfolios available up to 1994, and the fourth column uses only tradable factors. In the last column, we use Elastic Net regularization for factor selection instead of LASSO. The regularization parameters in each selection are chosen by 5-fold cross-validation.
Table 4: Factor Zoo

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<tr>
<th>id</th>
<th>Category</th>
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<th>Avg.Ret</th>
<th>Annual S.R.</th>
<th>Reference</th>
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<td>Sharpe (1964)</td>
</tr>
<tr>
<td>2</td>
<td>T</td>
<td>Beta</td>
<td>1973</td>
<td>-0.18%</td>
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<td>Fama and MacBeth (1973)</td>
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<td>3</td>
<td>V</td>
<td>Earnings to Price</td>
<td>1977</td>
<td>0.20%</td>
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<td>Basu (1977)</td>
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<td>4</td>
<td>V</td>
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<td>1982</td>
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<td>9.02%</td>
<td>Litzenberger and Ramaswamy (1982)</td>
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<tr>
<td>5</td>
<td>M</td>
<td>Unexpected Quarterly Earnings</td>
<td>1982</td>
<td>0.04%</td>
<td>7.90%</td>
<td>Rendleman et al. (1982)</td>
</tr>
<tr>
<td>6</td>
<td>V</td>
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<td>26.54%</td>
<td>Bondt and Thaler (1985)</td>
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<td>7</td>
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<td>1988</td>
<td>0.12%</td>
<td>13.39%</td>
<td>Bhandari (1988)</td>
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<td>8</td>
<td>T</td>
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<td>1989</td>
<td>0.12%</td>
<td>8.27%</td>
<td>Amihud and Mendelson (1989)</td>
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<td>9</td>
<td>IN</td>
<td>Cash Flow to Debt</td>
<td>1989</td>
<td>0.06%</td>
<td>12.17%</td>
<td>Ou and Penman (1989)</td>
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<td>10</td>
<td>IN</td>
<td>Current Ratio</td>
<td>1989</td>
<td>-0.01%</td>
<td>-0.49%</td>
<td>Ou and Penman (1989)</td>
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<td>11</td>
<td>IN</td>
<td>Change in Current Ratio</td>
<td>1989</td>
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<td>14.00%</td>
<td>Ou and Penman (1989)</td>
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<td>IN</td>
<td>Change in Quick Ratio</td>
<td>1989</td>
<td>0.03%</td>
<td>6.80%</td>
<td>Ou and Penman (1989)</td>
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<td>IN</td>
<td>Change Sales-to-Inventory</td>
<td>1989</td>
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<td>7.28%</td>
<td>Ou and Penman (1989)</td>
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<td>Quick Ratio</td>
<td>1989</td>
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<td>Ou and Penman (1989)</td>
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<td>IN</td>
<td>Sales to Cash</td>
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<td>-0.04%</td>
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<td>Ou and Penman (1989)</td>
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<td>-0.01%</td>
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<td>17</td>
<td>IN</td>
<td>Sales to Receivables</td>
<td>1989</td>
<td>0.15%</td>
<td>22.42%</td>
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<td>18</td>
<td>V</td>
<td>Depreciation / PP&amp;E</td>
<td>1992</td>
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<td>10.83%</td>
<td>Holthausen and Larcker (1992)</td>
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<td>1992</td>
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<td>11.90%</td>
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<td>20</td>
<td>T</td>
<td>Small Minus Big</td>
<td>1993</td>
<td>0.12%</td>
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<td>Fama and French (1993)</td>
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<td>21</td>
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<td>1993</td>
<td>0.32%</td>
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<td>T</td>
<td>Short-Term Reversal</td>
<td>1993</td>
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<td>23</td>
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<td>1994</td>
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<td>-0.71%</td>
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</table>

Note. The factor zoo contains 98 tradable and 1 nontradable (No.97) factors for monthly data from July 1980 to December 2016. In addition to these publicly available factors, we follow Fama and French (1993) to construct value-weighted portfolios as factors using firm characteristics collected in Green et al. (2016). For each characteristic therein, we sort all stocks into deciles based on their previous year-end values, then build and rebalance a long-short portfolio (top 30% - bottom 30% or 1-0 dummy difference) every June. For factor classification, “M” is Momentum, “V” is Value-versus-Growth, “T” is Investment, “P” is Profitability, “IN” is Intangibles, and “T” is Trading Frictions.
<table>
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<td>25</td>
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<td>Michaely et al. (1995)</td>
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<td>26</td>
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<td>27</td>
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<td>13.46%</td>
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<td>28</td>
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<td>36</td>
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<td>51</td>
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<td>2003</td>
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<td>53</td>
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<td>64</td>
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<td>R&amp;D to Market Capitalization</td>
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Figure 1: Factors Introduced in 2011-2016: Robustness to Tuning Parameters

Note. The figures provide heat maps for double-selection tests of factors introduced in 2011-2016, as in the first column of Table 1, using a wide range of tuning parameters, for the first LASSO stage on the X axis and for the second stage on the Y axis. Each factor corresponds to a row. For each factor, the left panel shows the t-statistics from our double selection method; the right panel indicates the number of controls selected from $h_2$ (the union of the 1st and 2nd selections).
Figure 2: Subsamples: Factor t-statistics

Note. The figure reports the histogram of individual factor t-statistics estimates across 2,000 bootstrap samples, for the factors introduced since 2011 (as in Table 1). We bootstrap our data over both the time-series and the cross-sectional (test assets) dimensions.
Figure 3: Subsamples: Factor Selection Rate

Note. The figure reports the control factor selection rates for the tests of Table 1 (i.e., the factors selected by the first LASSO step of the double-selection procedure), across bootstrap samples selected as in Figure 2. The figure shows, for each factor identified by the factor ID (on the X axis), in what fraction of the 2,000 samples that factor is selected by LASSO. The first 83 factors are the original factors; the next 83 factors are the squared factors and the last 82 are their interaction with Small Minus Big.
Internet Appendix for “Taming the Factor Zoo”

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College of Business  Yale School of Management  Booth School of Business
City University of Hong Kong  NBER and CEPR  University of Chicago

This Version: December 26, 2017

Abstract

This appendix contains Monte Carlo simulations and mathematical proofs.

Appendix A Simulation Evidence

One of the central advantages of our double-selection method is that it produces proper inference on the risk price \( \lambda_g \), taking explicitly into account the possibility that the model-selection step (based on LASSO) may mistakenly include some irrelevant factors or exclude useful factors in any finite sample.

In this section, we therefore study the finite-sample performance of our inference procedure using Monte Carlo simulations. In particular, we show that if one were to make inference on \( \lambda_g \) by selecting the control factors via standard LASSO (and ignoring potential mistakes in model selection), the omitted variable bias resulting from selection mistakes would yield incorrect inference about \( \lambda_g \). Instead, our double-selection procedure fully corrects for this problem in a finite sample and produces valid inference. In what follows, we first give details of the simulation procedure and then show the results of the Monte Carlo experiment.

A.1 Simulating the Data-Generating Process

We are interested in making inference on \( \lambda_g \), the vector of prices of risk of three factors in \( g_t \). \( g_t \) includes a useful factor (denoted as \( g_{1t} \)) as well as a useless factor and a redundant factor (denoted together as a \( 2 \times 1 \) vector \( g_{2t} \)). \( g_{2t} \) has zero risk price, that is, \( \lambda_{g_{2t}} = 0 \), but the covariance of the redundant factor is correlated with the cross section of expected returns. In our simulation, \( h_t \) is a

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large set of factors that includes 4 useful factors \( h_{1t} \), and \( p - 4 \) useless and redundant factors collected in \( h_{2t} \) (so the total dimension of \( h_t \) is \( p \)).

We simulate returns of test assets and factors according to the following steps:

1. Simulate \( C_e \) \((n \times d)\) and \( C_{h_1} \) \((n \times 4)\) independently from multivariate normal distributions.

2. Calculate \( C_{h_2} = \eta h_0 + C_{h_1} \beta_1 + C_e \), where \( C_e \) is simulated independently from an \( n \times (p - 4) \) multivariate normal distribution, \( \theta_0 \) is a \((p - 4) \times 1\) vector, and \( \theta_1 \) is a \((p - 4) \times 4\) matrix.

3. Calculate \( C_g \) from \( C_e \) and \( C_h = (C_{h_1} : C_{h_2}) \) using \( C_g = \iota_n \xi + C_h \chi^T + C_e \), where \( \chi \) is a \( d \times p \) matrix.

4. Calculate \( C_z \) using \( C_z = C_g - C_h \eta^T \), as implied from the DGP \( g_t = \eta h_t + z_t \) we aim to simulate, where \( \eta \) is a \( d \times p \) matrix.

5. Calculate \( E(r_t) \) using \( E(r_t) = \iota_n \gamma_0 + C_g \lambda_g + C_h \lambda_h \), where \( \lambda_g \) is a \( d \times 1 \) vector and \( \lambda_h \) is a \( p \times 1 \) vector.

6. Calculate \( \beta_g = C_z \Sigma_z^{-1} \) and \( \beta_h = C_h \Sigma_h^{-1} - \beta_g \eta \), as implied from the DGP of \( r_t \) we aim to simulate: \( r_t = E(r_t) + \beta_g g_t + \beta_h h_t + u_t \).

7. For each Monte Carlo trial, generate \( u_t \) from a Student’s t distribution with 5 degrees of freedom and a covariance matrix \( \Sigma_u \). Generate \( h_t \sim N_h(0, \Sigma_h) \), \( z_t \sim N_d(0, \Sigma_z) \), and calculate \( g_t \) and then \( r_t \) using the DGPs specified in Steps (4) and (6), respectively.

The total number of Monte Carlo trials is 5,000. Because we assume non-random selection of assets and that the randomness in the selection of test assets does not affect the inference to the first order, we simulate only once \( C_g, C_h \), and hence \( \beta_g, \beta_h \), in Steps (1) - (6), so that they are constant throughout the Monte Carlo trials in Step (7).

We calibrate our DGP to mimic the actual Fama-French 5-factor model. In particular, we calibrate \( \chi, \eta, \lambda, \Sigma_z \), the mean and covariance matrices of \( C_e, C_{h_1} \), as well as \( \Sigma_h \) to match the summary statistics (times series and cross-sectional \( R^2 \), factor-return covariances, etc.) of the Fama-French five factors estimated using characteristic-sorted portfolios, described in detail in Section 3. We calibrate a diagonal \( \Sigma_u \) to match the average time series \( R^2 \) for this 5-factor model. For redundant and useless factors, we calibrate their parameters using all the other factors in our data library, again described in detail in Section 3. We maintain the sparsity requirement on \( \chi, \eta, \) and \( \lambda \), by restricting the loadings of \( C_g \), \( E(r_t) \) and \( g \) on \( C_{h_2} \) and \( h_2 \) to be zero. We set to zero the loading of \( C_g \) on \( C_h \) for the useless factor in \( g_2 \). Moreover, we randomly simulate \( \theta_1 \) from normal distribution so that factors in \( h_2 \) are either redundant or (rather close to be) useless. We allow non-zero loading of \( g_2 \) on \( h_1 \), and the covariance matrix \( \Sigma_h \) to be non-diagonal, so that both useless and redundant
factors in $g_2$ and $h_2$ can be correlated with the true factors in $g_1$ and $h_1$: so they will command risk premia simply due to this correlation, even though they have zero risk prices because they do not affect marginal utility once the true factors are controlled for.

A.2 Simulation Results

We report here the results of various simulations from the model. We consider various settings with number of total factors $p = 25, 50, 100$, number of assets $n = 100, 200, 300$, and length of time series $T = 240, 360, 480$.

Figure A1 compares the asymptotic distributions of the proposed double-selection estimator with that of the single-selection estimator for the case $p = 100$, $n = 300$, and $T = 480$. The right side of the figure shows the distribution of the t-test for the price of risk $\lambda_g$ of the three factors (useful in the first row, redundant in the second row, and useless in the third row) when using the controls selected by standard LASSO (i.e., a single-selection-based estimator). The panels show that inference without double-selection adjustment displays substantial biases for useful and redundant factors and distortion from normality for all factors. The left side of the figure shows instead that our double-selection procedure produces an unbiased and asymptotically normal test, as predicted by Theorem 1.

Figure A2 plots the frequency with which each of the simulated factors is selected across simulations (with each bar corresponding to a different simulated factor, identified by its ID from 1 to 100). The top panel corresponds to the factors selected in the first LASSO selection, the second panel corresponds to the factors selected in the second selection, and the last panel corresponds to the union of the two.

Note that by construction, the true factors in $h_t$ are the first 4 (the fifth true factor is part of $g_t$). So if model selection were able to identify the right control factors in all samples perfectly, the first 4 bars should read 100%, while all other bars (corresponding to factors 5-100) should read 0%.

That is not the case in the simulations. While some factors are often selected by LASSO (top panel), not all are: factor 1 is selected in about 70% of the samples, and factor 3 less than 50% of the samples. Therefore, in a large fraction of samples, the control model would be missing some true factors, generating the omitted variable bias displayed in Figure A1. At the same time, LASSO often includes erroneously spurious factors – often more than 20 factors in total. The key to correct inference that our procedure achieves is that the two-step selection procedure minimizes the potential omitted factor bias.

Tables A1, A2, and A3 compare the biases and root-mean-squared errors (RMSEs) for double-selection (DS), single-selection (SS), and the OLS estimators of each entry of $\lambda_g$, respectively. All
regularization parameters are selected based on 5-fold cross-validation.

Not surprisingly, the bias of the SS is clearly visible when compared to DS and OLS for useful and redundant factors. In addition, DS outperforms SS and OLS in terms of their RMSEs in these scenarios. The efficiency gain of DS over OLS is particularly substantial when $p$ is large relative to $n$. When $p$ is equal to $n$, OLS becomes infeasible (because the number of regressors is $p + d$). For the useless factor, because SS does not suffer from a bias, its RMSE is the smallest among all. This result confirms the efficiency benefits of machine learning techniques over OLS. Although DS is in general less biased than SS, its main advantage relative to SS is in removing the distortions to inference, visible from the distribution of standardized statistics in Figure A1.

Overall, the simulation results confirm our econometric analysis: the DS estimator outperforms the benchmarks.
Table A1: Asymptotic Approximation Performance for $\lambda_{\text{useful}}$

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Panel B: RMSE

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Note. This table provides the biases and root-mean-squared errors (RMSE) of the estimates of the price of risk $\lambda$ of the useful factor from Monte Carlo simulations. DS is the double-selection estimator, SS is the single-selection estimator, and OLS is the ordinary least squares without selection. The regularization parameters in the LASSO are selected using 5-fold cross-validation. The true value $\lambda_{\text{useful}}$ is 16.76. Note that in cases of $n = p$, OLS is infeasible.
Table A2: Asymptotic Approximation Performance for $\lambda_{\text{redundant}}$

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Panel B: RMSE

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Note. This table provides the biases and root-mean-squared errors (RMSE) of the estimates of the price of risk $\lambda$ of the redundant factor from Monte Carlo simulations. DS is the double-selection estimator, SS is the single-selection estimator, and OLS is the ordinary least squares without selection. The regularization parameters in the LASSO are selected using 5-fold cross-validation. The true value $\lambda_{\text{redundant}}$ is 0. Note that in cases of $n = p$, OLS is infeasible.
Table A3: Asymptotic Approximation Performance for $\lambda_{\text{useless}}$

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Panel B: RMSE

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</tbody>
</table>

Note. This table provides the biases and root-mean-squared errors (RMSE) of the estimates of the price of risk $\lambda$ of the useless factor from Monte Carlo simulations. DS is the double-selection estimator, SS is the single-selection estimator, and OLS is the ordinary least squares without selection. The regularization parameters in the LASSO are selected using 5-fold cross-validation. The true value $\lambda_{\text{useless}}$ is 0. Note that in cases of $n = p$, OLS is infeasible.
Note. The figure presents the histograms of the standardized double-selection and single-selection estimates using estimated standard errors, compared with the standard normal density in solid dashed lines. The left panel reports the double-selection histograms, and the right panel the single-selection histograms. The top row reports the distribution of standardized estimates for a useful factor; the middle row for a redundant factor; the last row for a useless factor. In the simulation, we set $T = 480$, $n = 300$, and $p = 100$. The regularization parameters in each selection are chosen by 5-fold cross-validation.
Figure A2: Histograms of the Selected Variables

Note. The figure reports how often each factor is selected in each step of our double selection procedure (first and second panels corresponding to the first and second step, and their union in the bottom panel), in Monte Carlo simulations. Each factor corresponds to a number on the X axis. Factors 1 - 4 are part of the true factors in the DGP. Factors 5 - 100 are either redundant or close to be useless. We set $T = 480$, $n = 300$, and $p = 100$. The regularization parameters in each selection are chosen by 5-fold cross-validation.
Appendix B  Technical Details and Proofs

B.1 Notation

We summarize the notation used throughout. Let $e_i$ be a vector with 1 in the $i$th entry and 0 elsewhere, whose dimension depends on the context. Let $\mathbb{1}_k$ denote a $k$-dimensional vector with all entries being 1. We use $a \lor b$ to denote the max of $a$ and $b$, and $a \land b$ as their min for any scalars $a$ and $b$. We also use the notation $a \lesssim b$ to denote $a \leq K b$ for some constant $K > 0$; and $a \preceq_p b$ to denote $a = O_p(b)$. For any time series of vectors $\{a_t\}_{t=1}^T$, we denote $\bar{a} = T^{-1} \sum_{t=1}^T a_t$. In addition, we write $\bar{a}_t = a_t - \bar{a}$. We use the capital letter $A$ to denote the projection operator with respect to a matrix $A$. We also use the notation $A_{ij}$ to denote the $(i,j)$-th entry and 0 their min for any scalars $a$ and $b$. We use $\lambda_{\min}(A)$ and $\lambda_{\max}(A)$ to denote the minimum and maximum eigenvalues of $A$. We use $\|A\|_1$, $\|A\|_\infty$, $\|A\|_F$ to denote the $L_1$ norm, the $L_\infty$ norm, the operator norm (or $L_2$ norm), and the Frobenius norm of a matrix $A = (a_{ij})$, that is, $\max_j \sum_i |a_{ij}|$, $\max_i \sum_j |a_{ij}|$, $\sqrt{\lambda_{\max}(A^\top A)}$, and $\sqrt{\text{Tr}(A^\top A)}$, respectively. We also use $\|A\|_{\text{MAX}} = \max_{i,j} |a_{ij}|$ to denote the $L_\infty$ norm of $A$ on the vector space. When $a$ is a vector, both $\|a\|$ and $\|a\|_F$ are equal to its Euclidean norm. We use $\|a\|_0$ to denote $\sum_i 1_{\{a_i \neq 0\}}$. We also denote $\text{Supp}(a) = \{ i : a_i \neq 0 \}$. We write the projection operator with respect to a matrix $A$ as $\mathbb{P}_A = A (A^\top A)^{-1} A^\top$, and the corresponding annihilator as $M_A = \mathbb{I} - \mathbb{P}_A$, where $\mathbb{I}$ is the identity matrix whose size depends on the context. For a set of indices $I$, let $A[I]$ denote a sub-matrix of $A$, which contains all columns indexed in $I$.

B.2 Technical Assumptions

**Assumption B.1 (Sparsity)**. $\|\lambda_h\|_0 \leq s$, $\|\chi_j,\|_0 \leq s$, $\|\eta_j,\|_0 \leq s$, $1 \leq j \leq d$, for some $s$ such that $sn^{-1} \to 0$.

**Definition 1 (LASSO and Post-LASSO Estimators)**. We consider a generic linear regression problem with sparse coefficients:

$$
Y = X \beta + \varepsilon, \quad \text{subject to} \quad \|\beta\|_0 \leq s,
$$

where $Y$ is a $n \times 1$ vector, $X$ is a $n \times p$ matrix, $\beta$ is $p \times 1$ vector of parameters. We define the LASSO estimator as

$$
\bar{\beta} = \arg \min_{\beta} \left\{ n^{-1} \|Y - X \beta\|^2 + n^{-1} \tau \|\beta\|_1 \right\}.
$$

We define the Post-LASSO estimator $\bar{\beta}_{\widehat{I}}$ as

$$
\bar{\beta}_{\widehat{I}} = \arg \min_{\beta} \left\{ n^{-1} \|Y - X \beta\|^2 : \beta_j = 0, \quad j \notin \widehat{I} \right\},
$$

where $\widehat{I}$ is the set of indices of variables selected by a first-step LASSO, that is, $\widehat{I} = \text{Supp}(\bar{\beta})$. 

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We adopt a high-level assumption on the model selection properties of LASSO and the prediction error bounds of the Post-LASSO estimators in (7) and (8). Belloni and Chernozhukov (2013) provide more primitive conditions for these bounds to hold.

**Assumption B.2 (Properties of Post-LASSO Estimators).** The Post-LASSO estimators in (7) and (8) satisfy the following properties:

1. \( \hat{s} = |\hat{I}_1 \cup \hat{I}_2| \lesssim_p s. \)

2. Moreover, if \( \tau_0 \geq 2c \left\| \lambda_n^I C^I(t_n : \hC_h) \right\|_1 \), for some \( c > 1 \), then

\[
    n^{-1/2} \left\| \lambda_n \left( \bar{\gamma}_{\hat{I}_1} - \gamma_0 \right) + \hC_h \left( \bar{\lambda}_{\hat{I}_1} - \lambda_h \right) \right\| \lesssim_p sT^{-1/2}(\log(n \vee p \vee T))^{1/2} + \tau_0 s^{1/2}n^{-1}, \tag{B.1}
\]

where \( \gamma_0 = \gamma + \xi^T \lambda_y \) and \( \lambda_h = \chi^T \lambda_y + \lambda_h \) are the true parameter values given in (2) and (6). If \( \tau_j \geq 2c_j \left\| \epsilon^I C^I(t_n : \hC_h) \right\|_1 \), for some \( c_j > 1 \) and \( j = 1, 2, \ldots, d \), then

\[
    n^{-1/2} \left\| \lambda_n \left( \bar{\gamma}_{\hat{I}_2} - \gamma \right)^T + \hC_h \left( \bar{\lambda}_{\hat{I}_2} - \chi \right)^T \right\| \lesssim_p sT^{-1/2}(\log(n \vee p \vee T))^{1/2} + \|\tau\|_{\text{MAX}} s^{1/2}n^{-1}, \tag{B.2}
\]

where \( \tau = (\tau_1, \tau_2, \ldots, \tau_d)^T \), \( \xi \) and \( \chi \) are the true parameter values given in (6).

**Assumption B.2** gives a probabilistic upper bound on \( \hat{s} \). The prediction error bounds in (B.1) and (B.2) are more conservative than the standard results, because the regressors here are estimated. We provide a sketch of the proof for (B.1) in Appendix B.4, for which we need the following sparse eigenvalues assumption. The proof of (B.2) is similar and simpler. Our theoretical result below would also hold if other model selection procedures are employed, provided that they obey similar properties in Assumption B.2.

**Assumption B.3 (Sparse Eigenvalues).** There exist \( K_1, K_2 > 0 \) and a sequence \( l_n \to \infty \), such that with probability approaching 1,

\[
    K_1 \leq \phi_{\text{min}}(l_n s) \left[ n^{-1}(t_n : \hC_h)^I(t_n : \hC_h) \right] \leq \phi_{\text{max}}(l_n s) \left[ n^{-1}(t_n : \hC_h)^I(t_n : \hC_h) \right] \leq K_2,
\]

where we denote

\[
    \phi_{\text{min}}(k)[A] = \min_{1 \leq \|v\|_2 \leq k} \frac{v^T A v}{\|v\|^2}, \quad \text{and} \quad \phi_{\text{max}}(k)[A] = \max_{1 \leq \|v\|_2 \leq k} \frac{v^T A v}{\|v\|^2}.
\]

Assumption B.3 resembles one of the sufficient conditions that lead to desirable statistical properties of LASSO, which has been adopted by, e.g., Belloni et al. (2014). It implies the restricted eigenvalue condition proposed by Bickel et al. (2009).

**Assumption B.4 (Large Deviation Bounds).** The stochastic discount factor, the returns, and the factors satisfy

\[
    \|\bar{a}\|_{\text{MAX}} \lesssim_p T^{-1/2}(\log(n \vee p \vee T))^{1/2}, \quad \text{where} \ a \in \{m, v, z, u\}. \tag{B.3}
\]

\[
    \|T^{-1} \bar{A}B^T - \text{Cov}(a_t, b_t)\|_{\text{MAX}} \lesssim_p T^{-1/2}(\log(n \vee p \vee T))^{1/2}, \quad \text{where} \ A, B \in \{M, V, Z, U\}. \tag{B.4}
\]
Assumption B.4 imposes high-level assumptions on the large deviation type bounds, which can be verified using the same arguments as in Fan et al. (2011) under stationarity, ergodicity, strong mixing, and exponential-type tail conditions.

Next, we impose additional uniform bounds that impose restrictions on the cross-sectional dependence of the “residuals” in the covariance projection (6). Similar assumptions on factor loadings are employed by Giglio and Xiu (2016).

**Assumption B.5 (“Moment” Conditions).** The following restrictions hold:

\[
\| C_e \|_{\text{MAX}} \lesssim 1, \quad \| C_e^T t_n \|_{\text{MAX}} \lesssim n^{1/2}, \quad \| C_e^T C_h \|_{\text{MAX}} \lesssim n^{1/2}, \quad (B.5)
\]

\[
\| C_e^T \bar{u} \|_{\text{MAX}} \lesssim p \, n^{1/2} T^{-1/2}, \quad \| C_e^T \bar{V} \bar{V}^T \|_{\text{MAX}} \lesssim p \, n^{1/2} T^{1/2}, \quad (B.6)
\]

\[
\lambda_{\min}(n^{-1} C_e^T C_e) \geq K, \quad \| C_e^T (\beta_g \eta + \beta_h) \|_{\infty} \lesssim s n^{1/2}, \quad \| \beta_h \|_{\infty} \lesssim s. \quad (B.7)
\]

In addition, for \( a \in \{m, v, z, u\} \), it holds that

\[
\| \Sigma_a \|_{\text{MAX}} \lesssim 1, \quad \| C_a \|_{\text{MAX}} \lesssim 1. \quad (B.8)
\]

Finally, we impose a joint central limit theorem for \((z_t, \lambda^T v_t z_t) = (z_t, (1-\gamma_0 m_t) z_t)\). This can be verified by the standard central limit theory for dependent stochastic processes, if more primitive assumptions are satisfied, see, e.g., White (2000).

**Assumption B.6 (CLT).** The following results hold as \( T \to \infty \):

\[
T^{1/2} \left( \begin{array}{c}
\bar{Z} \\
- T^{-1} \gamma_0 \bar{Z} M^T - \Sigma_z \lambda g
\end{array} \right) \xrightarrow{L} N \left( \begin{array}{c}
0 \\
0
\end{array} , \begin{pmatrix}
\Pi_{11} & \Pi_{12} \\
\Pi_{12}^T & \Pi_{22}
\end{pmatrix} \right)
\]

where \( \Pi_{11}, \Pi_{12}, \) and \( \Pi_{22} \) are given by

\[
\Pi_{11} = \lim_{T \to \infty} \frac{1}{T} \sum_{t=1}^{T} \sum_{s=1}^{T} E(z_s z_t^T),
\]

\[
\Pi_{12} = \lim_{T \to \infty} \frac{1}{T} \sum_{t=1}^{T} \sum_{s=1}^{T} E(\lambda^T v_s z_s z_t^T),
\]

\[
\Pi_{22} = \lim_{T \to \infty} \frac{1}{T} \sum_{t=1}^{T} \sum_{s=1}^{T} E(\lambda^T v_s \lambda^T v_t z_s z_t^T).
\]

**Assumption B.7 (Selection for the Asymptotic Variance Estimator).** The Post-LASSO estimator \( \tilde{\eta}_I \) satisfies the usual bounds. That is, if \( \tilde{r}_j \geq 2 \tilde{c}_j \| H Z^T \|_{\infty}, \) for some \( \tilde{c}_j > 1, \) \( j = 1, 2, \ldots, d, \) then we have

\[
\| (\tilde{\eta}_I - \eta) H \| \lesssim_b s^{1/2} (\log(p \vee T))^{1/2}, \quad \text{and} \quad \| \tilde{\eta}_I - \eta \| \lesssim_b s^{1/2} T^{-1/2} (\log(p \vee T))^{1/2}.
\]
B.3 Proof of Main Theorems

Proof of Theorem 1. The estimator of $\lambda_g$ can be written in closed-form as

$$\hat{\lambda}_g = \left( \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \hat{C}_g \right)^{-1} \left( \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \hat{y} \right).$$

(B.9)

Moreover, by (2) and (5), we can relate $C_g$ and $\hat{C}_h$ to $\beta_g$ and $\beta_h$:

$$C_g = C_h \eta^\prime + C_z, \quad \text{where} \quad C_h = (\beta_g \eta + \beta_h) \Sigma_h, \quad C_z = \beta_g \Sigma_z.$$  

(B.10)

Using (3), (5), (B.10), and the fact that

$$\hat{C}_g - C_g = (\hat{C}_h - C_h) \eta^\prime + (\hat{C}_z - C_z),$$

$$\hat{C}_z - C_z = \beta_g \left( T^{-1} \hat{Z} \hat{Z}^\prime - \Sigma_z \right) + T^{-1} \hat{U} \hat{Z}^\prime + T^{-1} (\beta_g \eta + \beta_h) \hat{H} \hat{Z}^\prime,$$

$$\hat{C}_h - C_h = (\beta_g \eta + \beta_h) \left( T^{-1} \hat{H} \hat{H}^\prime - \Sigma_h \right) + T^{-1} \hat{U} \hat{H}^\prime + T^{-1} \beta_g \hat{Z} \hat{H}^\prime,$$

we obtain the following decomposition:

$$T^{1/2}(\hat{\lambda}_g - \lambda_g)$$

$$= \left( n^{-1} \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \hat{C}_g \right)^{-1} n^{-1} T^{1/2} \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \left( (C_g - \hat{C}_g) \lambda_g + C_h \lambda_h + \beta_g \bar{Z} + ((\beta_g \eta + \beta_h) \hat{h} + \bar{u}) \right)$$

$$= T^{1/2} \Sigma_z^{-1} \left( \bar{Z} - (T^{-1} \bar{Z} \bar{V}^\prime \lambda - \Sigma_z \lambda_g) \right)$$

$$+ \left( n^{-1} \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \hat{C}_g \right)^{-1} n^{-1} T^{1/2} \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \left( \bar{u} - T^{-1} \hat{U} \bar{V}^\prime \lambda \right)$$

$$+ n^{-1} T^{1/2} \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \beta_g (\hat{C}_g - \eta^\prime \Sigma_z^{-1} \bar{Z})$$

$$- n^{-1} T^{1/2} \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} (\beta_g \eta + \beta_h) \left( T^{-1} \hat{H} \bar{V}^\prime \lambda - \Sigma_h (\eta^\prime \lambda_g + \lambda_h) \right) - \bar{h}$$

$$+ n^{-1} T^{1/2} \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \bar{C}_h \lambda_h.$$  

We first analyze the leading term. Note that $\gamma_0 \tilde{M}^\prime = -\tilde{V}^\prime \lambda$, by Assumption B.6 and applying the Delta method, we have

$$T^{1/2} \left( \Sigma_z^{-1} \bar{Z} - \Sigma_z^{-1} \left( -T^{-1} \gamma_0 \tilde{Z} \tilde{M}^\prime - \Sigma_z \lambda_g \right) \right)$$

$$\xrightarrow{\mathcal{L}} \mathcal{N} \left( 0, \frac{1}{T} \sum_{t=1}^{T} \sum_{s=1}^{T} \mathbb{E} \left[ \left( 1 - \lambda^\prime v_t \right) \left( 1 - \lambda^\prime v_s \right) \Sigma_z^{-1} z_t z_s^\prime \Sigma_z^{-1} \right] \right).$$  

(B.11)

Next, we show that the reminder terms are of a smaller order. By (B.42), we have

$$n^{-1} T^{1/2} \left\| \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \left( \bar{u} - T^{-1} \hat{U} \bar{V}^\prime \lambda \right) \right\| \lesssim_p s \left( n^{-1/2} + T^{-1/2} \right) \log(n \vee p \vee T).$$

By (B.27), we have

$$n^{-1} T^{1/2} \left\| \hat{C}_g^\prime M_{(t_n, \hat{C}_h[\hat{p}])} \hat{C}_h \lambda_h \right\| \lesssim_p s^2 \left( n^{-1} T^{1/2} + T^{-1/2} \right) \log(n \vee p \vee T).$$
By (B.40), we have
\[
n^{-1}T^{1/2} \left\| \hat{C}^\top M_{(n, \hat{C}_h[\hat{h}])} (\beta_g \eta + \beta_h) \left( T^{-1} \bar{H} \bar{V} \bar{\lambda} - \Sigma_h (\eta \bar{\lambda}_g + \lambda_h) - \hat{h} \right) \right\|
\lesssim p s^2 \left( n^{-1/2} + T^{-1/2} \right) \log(n \lor p \lor T).
\]

By Assumption B.4, (B.11), and (B.35), we have
\[
n^{-1}T^{1/2} \left\| \hat{C}^\top M_{(n, \hat{C}_h[\hat{h}])} (\beta_g - \hat{C}_g \Sigma^{-1}_z) \left( \bar{z} - (T^{-1} \bar{Z} \bar{V} \bar{\lambda} - \Sigma_z \lambda_g) \right) \right\|
\lesssim n^{-1}T^{1/2} \left\| \hat{C}^\top M_{(n, \hat{C}_h[\hat{h}])} (\beta_g - \hat{C}_g \Sigma^{-1}_z) \right\| \left\| \bar{z} - (T^{-1} \bar{Z} \bar{V} \bar{\lambda} - \Sigma_z \lambda_g) \right\|
\lesssim p s \left( n^{-1/2} + T^{-1/2} \right) \log(n \lor p \lor T).
\]

This concludes the proof. \qed

**Proof of Theorem 2.** By the identical argument in the proof of Theorem 2 of Newey and West (1987), we have
\[
\frac{1}{T} \sum_{t=1}^{T} \sum_{r=1}^{T} Q_{tr} (1 - \lambda^\top v_t) (1 - \lambda^\top v_r) \left( z_t z_r^\top + z_r z_t^\top \right) \xrightarrow{p} \Sigma_\lambda \Sigma_\lambda.
\]

So applying the continuous mapping theorem, it is sufficient to show that
\[
\hat{\Sigma}_z \xrightarrow{p} \Sigma_z, \tag{B.12}
\]
\[
\bar{\Pi} - \frac{1}{T} \sum_{t=1}^{T} \sum_{r=1}^{T} Q_{tr} (1 - \lambda^\top v_t) (1 - \lambda^\top v_r) \left( z_t z_r^\top + z_r z_t^\top \right) \xrightarrow{p} 0, \tag{B.13}
\]
where
\[
Q_{tr} = \left( 1 - \frac{r - t}{q + 1} \right) 1_{\{|t-r| \leq q\}}, \quad \bar{\Pi} = \hat{\Sigma}_z \hat{\Pi} \hat{\Sigma}_z.
\]

To prove (B.12), we note that by Assumptions B.4 and B.7, we have
\[
\left\| \hat{\Sigma}_z - \Sigma_z \right\|_{\text{MAX}} \lesssim T^{-1/2} \| (\bar{\eta}^\top - \eta) H \|_{\text{MAX}} + T^{-1} \| (\bar{\eta}^\top - \eta) H \|^2 + \| T^{-1} Z Z^\top - \Sigma_z \|_{\text{MAX}}
\lesssim p s^{1/2} T^{-1/2} (\log(p \lor T))^{1/2} \| Z \|_{\text{MAX}} + s T^{-1} \log(p \lor T) + T^{-1/2} (\log(n \lor p \lor T))^{1/2}
= o_p(1). \tag{B.14}
\]

As to (B.13), we can decompose its left-hand side as
\[
\frac{1}{T} \sum_{t=1}^{T} \sum_{r=1}^{T} Q_{tr} (\hat{\lambda} - \lambda)^\top v_t (1 - \hat{\lambda}^\top v_r) \left( \hat{z}_t z_r^\top + \hat{z}_r z_t^\top \right) \tag{B.15}
\]
Analyzing each of these terms, we can obtain that

\[ + \frac{1}{T} \sum_{t=1}^{T} \sum_{r=1}^{T} Q_{tr}(1 - \lambda^T v_t)(\hat{\lambda} - \lambda)^T v_r (\hat{z}_t \hat{z}_r^T + \hat{z}_r \hat{z}_t^T) \]

(B.16)

\[ + \frac{1}{T} \sum_{t=1}^{T} \sum_{r=1}^{T} Q_{tr}(1 - \lambda^T v_t)(1 - \lambda^T v_r) ((\hat{z}_t - z_t) \hat{z}_r^T + (\hat{z}_r - z_r) \hat{z}_t^T) \]

(B.17)

\[ + \frac{1}{T} \sum_{t=1}^{T} \sum_{r=1}^{T} Q_{tr}(1 - \lambda^T v_t)(1 - \lambda^T v_r) (z_t (\hat{z}_r - z_r)^T + z_r (\hat{z}_t - z_t)^T). \]

(B.18)

where we use

\[ \| \frac{1}{T} \sum_{t=1}^{T} \sum_{r=1}^{T} Q_{tr}(\hat{\lambda} - \lambda)^T v_t (1 - \hat{\lambda}^T v_r) (\hat{z}_t \hat{z}_r^T + \hat{z}_r \hat{z}_t^T) \| \leq q T^{-1} \| \hat{Z} \| \| \hat{v}_T \| \| (\hat{\lambda} - \lambda)^T \| \| \hat{Z} \| \| \hat{\lambda} - \lambda \| \| V \| \leq q s^{1/2}(T^{-1/2} + n^{-1/2}) \| V \| \| Z \| \]

(B.14)

which hold by (B.14), Assumption B.4, and Lemma 7. This concludes the proof.

\[ \square \]

B.4 Proof of Lemmas

Proof of (B.1). We provide a sketch of the proof, as it is very similar to Belloni and Chernozhukov (2013). With respect to the optimization problem (7), we define

\[ Q(\gamma, \lambda) = n^{-1} \| \tilde{r} - \nu_n \gamma - \hat{C}_h \lambda \|^2. \]
We denote the solution to this problem as \( \tilde\gamma \) and \( \tilde\lambda \). Let \( \delta = \tilde\lambda - \tilde\lambda_h \). Note by (5) and (2), we have

\[
E(r_t) = t_n \bar{\gamma}_0 + C_h \bar{\lambda}_h + C_e \lambda_g, \quad \text{and} \quad \bar{r} = E(r_t) + \beta_g \bar{\gamma} + \beta_h \bar{\lambda} + \bar{u}.
\]

By direct calculations, we have

\[
\begin{align*}
Q(\tilde\gamma, \tilde\lambda) - Q(\gamma_0, \tilde\lambda_h) - n^{-1} \left\| t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right\|^2 &= - 2n^{-1} \left( \bar{r} - t_n \gamma_0 - \tilde{C}_h \lambda_h \right)^T \left( t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right) \\
&= - 2n^{-1} \left( \beta_g \bar{\gamma} + \beta_h \bar{\lambda} + \bar{u} + (C_h - \tilde{C}_h) \tilde{\lambda}_h + C_e \lambda_g \right)^T \left( t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right) \\
&\geq - 2n^{-1} \left\| \beta_g \bar{\gamma} + \beta_h \bar{\lambda} + \bar{u} + (C_h - \tilde{C}_h) \tilde{\lambda}_h \right\| \left\| t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right\| \\
&\quad - 2n^{-1} \left( C_e \lambda_g \right)^T \left( t_n : \tilde{C}_h \right) \left\| (\tilde\gamma - \gamma_0) : \delta^T \right\|_1 \\
&\geq - 2n^{-1} \left\| \beta_g \bar{\gamma} + \beta_h \bar{\lambda} + \bar{u} + (C_h - \tilde{C}_h) \tilde{\lambda}_h \right\| \left\| t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right\| \\
&\quad - \tau_0 K^{-1} n^{-1} (|\tilde\gamma - \gamma_0| + \|\delta_I\|_1 + \|\delta_{I^c}\|_1),
\end{align*}
\]

where \( I \) is the set of non-zeros in \( \tilde{\lambda}_h \), \( I^c \) is its complement, and \( \delta_I \) is a sub-vector of \( \delta \) with all entries taken from \( I \).

On the other hand, by definition of \( \tilde\gamma \) and \( \tilde\lambda \), we have

\[
\begin{align*}
Q(\tilde\gamma, \tilde\lambda) - Q(\gamma_0, \tilde\lambda_h) \leq & \tau_0 n^{-1} \left( \left\| \gamma_0 : \tilde{\lambda}_h^T \right\|_1 - \left\| \tilde{\gamma} : \tilde{\lambda}_h^T \right\|_1 \right) \\
& \leq \tau_0 n^{-1} (|\tilde\gamma - \gamma_0| + \|\delta_I\|_1 - \|\delta_{I^c}\|_1).
\end{align*}
\]

Therefore, we obtain

\[
\begin{align*}
n^{-1} \left\| t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right\|^2 &= - \tau_0 c^{-1} n^{-1} (|\tilde\gamma - \gamma_0| + \|\delta_I\|_1 + \|\delta_{I^c}\|_1) \\
&\quad - 2n^{-1} \left\| \beta_g \bar{\gamma} + \beta_h \bar{\lambda} + \bar{u} + (C_h - \tilde{C}_h) \tilde{\lambda}_h \right\| \left\| t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right\| \\
&\leq \tau_0 n^{-1} (|\tilde\gamma - \gamma_0| + \|\delta_I\|_1 - \|\delta_{I^c}\|_1), \tag{B.19}
\end{align*}
\]

where we use the fact that

\[
\tau_0 \geq 2c \left\| \lambda^T C_e^T (t_n : \tilde{C}_h) \right\|_1.
\]

If it holds that

\[
n^{-1} \left\| t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right\| - 2n^{-1} \left\| \beta_g \bar{\gamma} + \beta_h \bar{\lambda} + \bar{u} + (C_h - \tilde{C}_h) \tilde{\lambda}_h \right\| < 0,
\]

we can establish that

\[
n^{-1/2} \left\| t_n (\tilde\gamma - \gamma_0) + \tilde{C}_h \delta \right\| \lesssim_p s T^{-1/2} (\log(n \vee p \vee T))^{1/2},
\]
where we use the fact that
\begin{align}
  n^{-1/2} \|\beta g\| &\lesssim \|\beta\|_{\text{MAX}} \|\tilde{g}\|_{\text{MAX}} \lesssim_p T^{-1/2}, \\
  n^{-1/2} \|\bar{u}\| &\lesssim \|\bar{u}\|_{\text{MAX}} \lesssim_p T^{-1/2} (\log(n \vee p \vee T))^{1/2}, \\
  n^{-1/2} \|\beta_h \bar{h}\| &\lesssim \|\beta_h\|_{\infty} \|\bar{h}\|_{\text{MAX}} \lesssim_p sT^{-1/2} (\log(n \vee p \vee T))^{1/2}, \\
  n^{-1/2} \|C_h - \tilde{C}_h\| \hat{\lambda}_h &\lesssim \|C_h - \tilde{C}_h\|_{\text{MAX}} \|\hat{\lambda}_h\|_1 \lesssim_p sT^{-1/2} (\log(n \vee p \vee T))^{1/2}.
\end{align}

Otherwise, from (B.19) it follows that
\[-c^{-1}(\tilde{\gamma} - \tilde{\gamma}_0) + \|\delta_I\|_1 + \|\delta_{I^c}\|_1 \leq |\tilde{\gamma} - \tilde{\gamma}_0| + \|\delta_I\|_1 - \|\delta_{I^c}\|_1,
\]
which leads to, writing \(\bar{c} = (c+1)(c-1)^{-1}\),
\[\|\delta_{I^c}\| \leq \bar{c}(|\tilde{\gamma} - \tilde{\gamma}_0| + \|\delta_I\|_1).
\]
Then by (B.19) again as well as the restricted eigenvalue condition in Belloni and Chernozhukov (2013), we obtain
\[
\left\|\lambda_n(\tilde{\gamma} - \tilde{\gamma}_0) + \tilde{C}_h \delta\right\|^2 - 2\left\|\beta g\tilde{g} + \beta_h \tilde{h} + \bar{u} + (C_h - \tilde{C}_h) \hat{\lambda}_h\right\| \lambda_n(\tilde{\gamma} - \tilde{\gamma}_0) + \tilde{C}_h \delta
\leq (1 + c^{-1}) \tau_0 (|\tilde{\gamma} - \tilde{\gamma}_0| + \|\delta_I\|_1) \lesssim \tau_0 s^{1/2} n^{-1/2} \left\|\lambda_n(\tilde{\gamma} - \tilde{\gamma}_0) + \tilde{C}_h \delta\right\|.
\]
Therefore, we have
\[
n^{-1/2} \left\|\lambda_n(\tilde{\gamma} - \tilde{\gamma}_0) + \tilde{C}_h \delta\right\| \lesssim n^{-1/2} \left\|\beta g\tilde{g} + \beta_h \tilde{h} + \bar{u} + (C_h - \tilde{C}_h) \hat{\lambda}_h\right\| + \tau_0 s^{1/2} n^{-1}
\lesssim_p sT^{-1/2} (\log(n \vee p \vee T))^{1/2} + \tau_0 s^{1/2} n^{-1}.
\]
The Post-LASSO estimator converges at the same rate following the same arguments as in Belloni and Chernozhukov (2013).

\[\boxdot\]

**Lemma 1.** Under Assumptions B.1, B.2, B.4, B.5, we have
\begin{align}
n^{-1/2} \left\|\mathbb{M}_{(\ell_n, \tilde{C}_h[I])} \tilde{C}_h \chi^T\right\| &\lesssim_p s n^{-1/2} + T^{-1/2} (\log(n \vee p \vee T))^{1/2}, \\
n^{-1/2} \left\|\mathbb{M}_{(\ell_n, \tilde{C}_h[I])} \tilde{C}_h \lambda_h\right\| &\lesssim_p s n^{-1/2} + T^{-1/2} (\log(n \vee p \vee T))^{1/2}.
\end{align}

**Proof of Lemma 1.** Using the fact that \(\hat{I}_2 \subseteq \hat{I}\) and by (B.2), we have
\[
n^{-1/2} \left\|\mathbb{M}_{(\ell_n, \tilde{C}_h[I])} \tilde{C}_h \chi^T\right\| = n^{-1/2} \left\|\mathbb{M}_{(\ell_n, \tilde{C}_h[I])} (\tilde{C}_h \chi^T + \lambda_n \xi^T)\right\| \leq n^{-1/2} \left\|\mathbb{M}_{(\ell_n, \tilde{C}_h[I_2])} (\tilde{C}_h \chi^T + \lambda_n \xi^T)\right\|
\leq n^{-1/2} \left\|\lambda_n (\xi - \xi_{I_2})^T + \tilde{C}_h \chi^T - \tilde{C}_h \chi_{I_2}^T\right\|
\lesssim_p s T^{-1/2} (\log(n \vee p \vee T))^{1/2} + \|\tau\|_{\text{MAX}} s^{1/2} n^{-1}.
\]
Since by Assumptions B.4 and B.5, our choice of $\tau$ satisfies:

$$n^{-1} \| \tau \|_{\text{MAX}} \lesssim n^{-1} \max_{1 \leq j \leq d} \left\| e_j \mathbf{C}_e \mathbf{C}_h \right\|_1 \lesssim n^{-1} \| \mathbf{C}_e \mathbf{C}_h \|_{\text{MAX}} + n^{-1} \left\| \mathbf{C}_e (\mathbf{C}_h - \mathbf{C}_h) \right\|_{\text{MAX}} \lesssim_p (n^{-1/2} + T^{-1/2}) (\log(n \vee p \vee T))^{1/2}. \quad (B.26)$$

This concludes the proof of (B.24).

Similarly, to prove (B.25), by (B.1) we have

$$n^{-1/2} \left\| M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} (\mathbf{C}_h \tilde{\lambda}_h + \tau_n \tilde{\gamma}_0) \right\| \leq n^{-1/2} \left\| (\tau_n : \mathbf{C}_h) (\tilde{\gamma}_1 - \tilde{\gamma}_0 : (\tilde{\lambda}_1 - \tilde{\lambda}_h)^\top) \right\| \lesssim_p sT^{-1/2} (\log(n \vee p \vee T))^{1/2} + \tau_0 s^{1/2} n^{-1}.$$

Because we can select $\tau_0$ that satisfies

$$n^{-1} \tau_0 \leq n^{-1} \left\| \lambda_g \mathbf{C}_e \right\|_1 (\tau_n : \mathbf{C}_h) \leq n^{-1} \left\| \lambda_g \mathbf{C}_e \right\|_1 + n^{-1} \left\| \lambda_g \mathbf{C}_e \mathbf{C}_h \right\|_{\text{MAX}},$$

hence it follows that

$$n^{-1/2} \left\| M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} (\mathbf{C}_h (\lambda_h + \chi^\top \lambda_g + \tau_n \gamma_0)) \right\| \lesssim_p s(n^{-1/2} + T^{-1/2}) (\log(n \vee p \vee T))^{1/2}.$$

By the triangle inequality and $M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \tau_n = 0$, we have

$$\left\| M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} (\mathbf{C}_h (\lambda_h + \chi^\top \lambda_g) + \tilde{\tau}_n \gamma_0) \right\| + \left\| M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \mathbf{C}_h \chi^\top \right\| \left\| \lambda_g \right\|,$$

which, combined with (B.24) and $\| \lambda_g \| \lesssim 1$, lead to the conclusion. \qed

**Lemma 2.** Under Assumptions B.1, B.2, B.3, B.4, B.5, we have

$$n^{-1} \left\| \mathbf{C}_e M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \mathbf{C}_h \lambda_h \right\| \lesssim_p s^2 (n^{-1} + T^{-1}) \log(n \vee p \vee T). \quad (B.27)$$

**Proof of Lemma 2.** We note by (6) that

$$\tilde{\mathbf{C}}_g = \tilde{\mathbf{C}}_h \chi^\top + \tilde{\mathbf{C}}_g - \mathbf{C}_g + \tau_n \xi^\top + (\mathbf{C}_h - \tilde{\mathbf{C}}_h) \chi^\top + \mathbf{C}_e,$$  \quad (B.28)

thereby it follows

$$n^{-1} \left\| \mathbf{C}_e M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \mathbf{C}_h \lambda_h \right\| \leq n^{-1} \left\| \chi^\top \left[ M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \tilde{\mathbf{C}}_h \lambda_h \right] \right\| + n^{-1} \left\| \mathbf{C}_e M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \tilde{\mathbf{C}}_h \lambda_h \right\| + n^{-1} \left\| (\tilde{\mathbf{C}}_g - \mathbf{C}_g + (\mathbf{C}_h - \tilde{\mathbf{C}}_h) \chi^\top)^\top M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \tilde{\mathbf{C}}_h \lambda_h \right\|.$$

On the one hand, by Lemma 1, we have

$$n^{-1} \left\| \chi^\top \left[ M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \tilde{\mathbf{C}}_h \lambda_h \right] \right\| \leq n^{-1/2} \left\| M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \tilde{\mathbf{C}}_h \lambda_h \right\| n^{-1/2} \left\| M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \tilde{\mathbf{C}}_h \lambda_h \right\| + n^{-1} \left\| (\tilde{\mathbf{C}}_g - \mathbf{C}_g + (\mathbf{C}_h - \tilde{\mathbf{C}}_h) \chi^\top)^\top M_{(\tau_n, \mathbf{C}_h [\tilde{T}_1])} \tilde{\mathbf{C}}_h \lambda_h \right\|.$$
Using (B.5) and Assumption B.4, it follows that
\[ \frac{\lambda_0}{C_{\text{e}}} = \arg \min_{\lambda} \| C_{\text{e}} (\lambda_0 - \hat{\lambda}_h) \|, \]
where \( \hat{\lambda}_h = \arg \min_{\lambda} \| (\gamma_0 - \hat{\lambda}_h) \|. \]

Finally, by (B.25) we have
\[
\left\| (\gamma_0 - \hat{\gamma}_0 : \lambda_h^T - \hat{\lambda}_h^T) \right\| \leq (s + \bar{s} + 1)^{1/2} \left\| (\gamma_0 - \hat{\gamma}_0 : \lambda_h^T - \hat{\lambda}_h^T) \right\|.
\]

Combining (B.30), (B.31), and (B.32), we obtain
\[
n^{-1} \left\| C_{\text{e}}^\top M_{(\omega, \hat{C}_h(\hat{\lambda}))} \hat{C}_h \lambda_h \right\| \lesssim_p s^{3/2} (n^{-1} + T^{-1}) \log(n \vee p \vee T).
\]

Finally, by (B.25) we have
\[
n^{-1} \left\| (\hat{C}_g - C_g + (C_h - \hat{C}_h) \gamma^T) M_{(\omega, \hat{C}_h(\hat{\lambda}))} \hat{C}_h \lambda_h \right\|
\leq \left\| (\hat{C}_g - C_g + (C_h - \hat{C}_h) \gamma^T) \right\|_{\text{MAX}} \left\| M_{(\omega, \hat{C}_h(\hat{\lambda}))} \hat{C}_h \lambda_h \right\|
\leq_p s^2 (n^{-1/2} T^{-1/2} + T^{-1}) (\log(n \vee p \vee T))^{1/2}.
\]

The above estimate, along with (B.33) and (B.29), conclude the proof of (B.27).
Lemma 3. Under Assumptions B.1, B.2, B.3, B.4, B.5, we have

\begin{align*}
n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| &\preceq_p s (n^{-1/2} + T^{-1/2}) (\log (n \lor p \lor T))^{1/2}. \tag{B.34} \\
n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} (\beta_g - \hat{C}_g \Sigma_g^{-1} \hat{C}_h) \right\| &\preceq_p s (n^{-1/2} + T^{-1/2}) (\log (n \lor p \lor T))^{1/2}. \tag{B.35}
\end{align*}

Proof of Lemma 3. (i) By (6), we have

\begin{align*}
n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| &\leq n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| + n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| \\
&\leq n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| n^{-1/2} \left\| \hat{C}_h \eta^T \right\| \\
&\preceq_p s (n^{-1/2} + T^{-1/2}) (\log (n \lor p \lor T))^{1/2}, \tag{B.36}
\end{align*}

where we use the fact that \( C_g = C_h \eta^T + C_z \), and that

\[ n^{-1/2} \left\| \hat{C}_h \eta^T \right\| \preceq \left\| \hat{C}_h \eta^T \right\|_{\text{MAX}} \preceq \left\| C_g \right\|_{\text{MAX}} + \left\| C_z \right\|_{\text{MAX}} \preceq 1. \]

In addition, we have

\[ n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| \leq n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| + n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\|. \]

To bound the first term, we have

\[ n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| \preceq n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| \| \eta \|_{\infty} \preceq_p s n^{-1/2} (\log (n \lor p \lor T))^{1/2}. \]

As to the second term, using (B.32) we obtain

\[ n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\| \]

\[ \preceq (1 + \delta) \phi_{\min}^{-1} (\delta + 1) \left[ n^{-1} \left\| (t_n : \hat{C}_h[\hat{I}]) \right\|_{\text{MAX}} n^{-1} \left\| \hat{C} \hat{W}_{\{t_n, \hat{C}_h[\hat{I}]\}} \hat{C}_h \eta^T \right\|_{\text{MAX}} \right. \]

\[ \preceq_p s (n^{-1/2} + T^{-1/2}) (\log (n \lor p \lor T))^{1/2}, \]

where we also use \( \left\| \hat{C}_h \eta^T \right\|_{\text{MAX}} \preceq \left\| C_g \right\|_{\text{MAX}} + \left\| C_z \right\|_{\text{MAX}} \preceq 1. \)
Therefore, we have
\[
n^{-1} \left\| C_{\epsilon}^T M_{(\tau_n, \hat{C}_h[\hat{l}])} C_h \eta^T \right\|_p \lesssim_p n^{-1/2} + T^{-1/2} (\log(n \lor p \lor T))^{1/2}. \tag{B.37}
\]
Similarly, because we have
\[
n^{-1} \left\| \left( \hat{C}_g - C_g \right)^T + \chi \left( C_h - \hat{C}_h \right)^T \right\| C_h \eta^T \leq \left\| \left( \hat{C}_g - C_g \right)^T + \chi \left( C_h - \hat{C}_h \right)^T \right\|_{\text{MAX}} \left\| C_h \eta^T \right\|_{\text{MAX}} \lesssim_p sT^{-1/2} (\log(n \lor p \lor T))^{1/2},
\]
and recall that \( \beta_g = C_z \Sigma_z^{-1} \), so we have
\[
n^{-1} \left\| \hat{C}_g \right\|_{\text{MAX}} \left\| C_z - \hat{C}_z \right\|_{\text{MAX}} \left\| \Sigma_z^{-1} \right\| \lesssim_p T^{-1/2} (\log(n \lor p \lor T))^{1/2}, \tag{B.38}
\]
Using Assumption B.4 and \( \left\| M_{(\tau_n, \hat{C}_h[\hat{l}])} \right\| \leq 1 \), we have
\[
n^{-1} \left\| \hat{C}_g \right\|_{\text{MAX}} \left\| C_z - \hat{C}_z \right\|_{\text{MAX}} \left\| \Sigma_z^{-1} \right\| \lesssim_p T^{-1/2} (\log(n \lor p \lor T))^{1/2}, \tag{B.38}
\]
where we also use the fact that
\[
\left\| \Sigma_z^{-1} \right\| \leq \lambda_{\min}^{-1}(\Sigma_z) \lesssim 1, \quad \hat{C}_g \right\|_{\text{MAX}} \leq \left\| C_g \right\|_{\text{MAX}} + \left\| C_g \right\|_{\text{MAX}} \lesssim 1.
\]
Similarly, we obtain
\[
n^{-1} \left\| \hat{C}_g \right\|_{\text{MAX}} \left\| C_z - \hat{C}_z \right\|_{\text{MAX}} \left\| \Sigma_z^{-1} \right\| \lesssim_p sT^{-1/2} (\log(n \lor p \lor T))^{1/2}. \tag{B.39}
\]
Combining (B.38), (B.39), and (B.34) concludes the proof. 

\[\square\]
Lemma 4. Under Assumptions B.1, B.2, B.3, B.4, B.5, we have

\[ n^{-1} \left\| \hat{C}^T M_{(t_n, \hat{c}_h[\bar{I}])}(\beta_g \eta + \beta_h) \left( T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \right) \right\| \leq_p s^2 (n^{-1/2} T^{-1/2} + T^{-1}) \log(n \lor p \lor T). \] (B.40)

Proof of Lemma 4. From (B.24) and Assumption B.4, it follows that

\[ n^{-1} \left\| \chi \hat{C}^T M_{(t_n, \hat{c}_h[\bar{I}])}(\beta_g \eta + \beta_h) \left( T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \right) \right\| \leq n^{-1/2} \left\| \chi \hat{C}^T M_{(t_n, \hat{c}_h[\bar{I}])} \right\| \| \beta_g \eta + \beta_h \|_\infty \left( \| T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) \|_{\text{MAX}} + \| \tilde{h} \|_{\text{MAX}} \right) \leq_p s^2 (n^{-1/2} T^{-1/2} + T^{-1}) \log(n \lor p \lor T). \] (B.41)

Next, by triangle inequality, we have

\[ n^{-1} \left\| C^T e M_{(t_n, \hat{c}_h[\bar{I}])}(\beta_g \eta + \beta_h) \left( T^{-1} \tilde{H} \tilde{Z}^\top \lambda_g + (T^{-1} \tilde{H} \tilde{H}) - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \right) \right\| \leq n^{-1} \left\| C^T e (\beta_g \eta + \beta_h) \left( T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \right) \right\| + n^{-1} \left\| C^T e M_{(t_n, \hat{c}_h[\bar{I}])}(\beta_g \eta + \beta_h) \left( T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \right) \right\|. \]

For the first term, by Assumption B.5 we have

\[ n^{-1} \left\| C^T e (\beta_g \eta + \beta_h) \left( T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \right) \right\| \leq n^{-1} \left\| C^T e (\beta_g \eta + \beta_h) \|_\infty \| (T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h}) \|_{\text{MAX}} \leq_p s n^{-1/2} T^{-1/2} (\log(n \lor p \lor T))^{1/2}. \]

For the second term, we use Assumptions B.1, B.3, B.4, and (B.32),

\[ n^{-1} \left\| C^T e M_{(t_n, \hat{c}_h[\bar{I}])}(\beta_g \eta + \beta_h) \left( T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \right) \right\| \leq (1 + \tilde{s}) \phi_{\text{min}}^{-1}(\tilde{s} + 1) \left\| n^{-1}(t_n : \hat{c}_h[\bar{I}]) \right\| n^{-1} \left\| C^T e (t_n : \hat{c}_h[\bar{I}]) \right\|_{\text{MAX}} \times \left\| (t_n : \hat{c}_h[\bar{I}]) \right\|_{\text{MAX}} \| \beta_g \eta + \beta_h \|_\infty \| T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \|_{\text{MAX}} \leq_p s^2 (n^{-1/2} T^{-1/2} + T^{-1}) \log(n \lor p \lor T). \]

Finally, by Assumptions B.1 and B.4, we have

\[ n^{-1} \left\| \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi \right)^T M_{(t_n, \hat{c}_h[\bar{I}])}(\beta_g \eta + \beta_h) \left( T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \right) \right\| \leq \left\| \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi \right)^T \right\|_{\text{MAX}} \| \beta_g \eta + \beta_h \|_\infty \| T^{-1} \tilde{H} \tilde{V}^\top \lambda - \Sigma_h(n^\top \lambda_g + \lambda_h) - \tilde{h} \|_{\text{MAX}} \leq_p s^2 T^{-1} \log(n \lor p \lor T). \]

The conclusion then follows from (B.28). □
Lemma 5. Under Assumptions B.1, B.2, B.3, B.4, we have

$$n^{-1} \left\| \hat{C}_g^T M_{(\ell_n \cdot \hat{C}_h[\hat{T}])} (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\| \lesssim_p s(n^{-1/2}T^{-1/2} + T^{-1}) \log(n \lor p \lor T). \quad (B.42)$$

Proof of Lemma 5. Note that by (B.24), we have

$$n^{-1} \left\| \chi \hat{C}_h^T M_{(\ell_n \cdot \hat{C}_h[\hat{T}])} (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\| \leq n^{-1/2} \left\| \mathcal{M}_{(\ell_n \cdot \hat{C}_h[\hat{T}])} \hat{C}_h \chi^T \right\| n^{-1/2} \| \hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda \|

\lesssim_p s(n^{-1/2}T^{-1/2} + T^{-1}) \log(n \lor p \lor T),$$

where we use the following estimates as a result of Assumptions B.1 and B.4:

$$n^{-1/2} \| \hat{u} \| \lesssim \| \hat{u} \|_{\text{MAX}} \lesssim_p T^{-1/2} (\log n \lor p \lor T)^{1/2},$$

$$n^{-1/2} \| T^{-1} \hat{U} \hat{V}^T \lambda \| \lesssim \| T^{-1} \hat{U} M^T \gamma_0 \|_{\text{MAX}} \lesssim_p T^{-1/2} (\log(n \lor p \lor T))^{1/2}.$$ 

Moreover, by triangle inequality, we have

$$n^{-1} \left\| C_e^T M_{(\ell_n \cdot \hat{C}_h[\hat{T}])} (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\|

\leq n^{-1} \left\| C_e^T (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\| + n^{-1} \left\| C_{e_T}^T M_{(\ell_n \cdot \hat{C}_h[\hat{T}])} (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\|$$

For the first term, we have

$$n^{-1} \left\| C_e^T (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\| \leq n^{-1} \| C_e^T \hat{u} \| + T^{-1} n^{-1} \| C_e^T \hat{U} \hat{V}^T \lambda \| \lesssim_p s n^{-1/2} T^{-1/2}.$$

As to the second term, using Assumption B.3 and (B.32) we have

$$n^{-1} \left\| C_{e_T}^T M_{(\ell_n \cdot \hat{C}_h[\hat{T}])} (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\|

= n^{-1} \left\| C_{e_T}^T (\ell_n : \hat{C}_h[\hat{T}]) (\ell_n : \hat{C}_h[\hat{T}])^T (\ell_n : \hat{C}_h[\hat{T}])^{-1} (\ell_n : \hat{C}_h[\hat{T}])^T (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\|

\lesssim_s n^{-1} \left\| C_{e_T}^T (\ell_n : \hat{C}_h[\hat{T}]) \right\|_{\text{MAX}} n^{-1} \left\| (\ell_n : \hat{C}_h[\hat{T}])^T (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\|_{\text{MAX}}

\lesssim_p s(n^{-1/2}T^{-1/2} + T^{-1}) \log(n \lor p \lor T),$$

where we also use the following

$$n^{-1} \left\| (\ell_n : \hat{C}_h)^T (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\|_{\text{MAX}} \leq \left( \left\| \hat{C}_h - C_h \right\|_{\text{MAX}} + \| (\ell_n : C_h) \|_{\text{MAX}} \right) \| \hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda \|_{\text{MAX}}

\lesssim_p T^{-1/2} (\log(n \lor p \lor T))^{1/2}.$$ 

Finally, we note that

$$n^{-1} \left\| (\hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T) M_{(\ell_n \cdot \hat{C}_h[\hat{T}])} (\hat{u} - T^{-1} \hat{U} \hat{V}^T \lambda) \right\|

\lesssim \left\| \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi \right\|_{\text{MAX}} \| \hat{u} - T^{-1} \hat{U} M^T \|_{\text{MAX}} \lesssim_p sT^{-1} \log(n \lor p \lor T).$$

This concludes the proof. \(\square\)
Lemma 6. Under Assumptions B.1, B.2, B.3, B.4, B.5, we have

$$n \left( \hat{C}^T \hat{M}_{(\hat{t}_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_g \right)^{-1} \lesssim p.$$  

Proof of Lemma 6. Note that by (B.28), we have

$$\hat{C}^T \hat{M}_{(\hat{t}_n; \hat{C}_{\hat{h}}[\hat{I}]}) \hat{C}_g$$

$$= C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} C_e + C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_h \chi^T + \chi C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_e + \chi \hat{C}^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_h \chi^T$$

$$+ C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right) + \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right)^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} C_e$$

$$+ \chi \hat{C}^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right) + \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right)^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_h \chi^T$$

$$+ \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right)^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right).$$

There are 9 terms in total on the right-hand side. By (B.24), we have

$$n^{-1} \left\| \chi C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} C_e \right\| = n^{-1} \left\| C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_h \chi^T \right\| \lesssim \left\| C_e \right\| \max n^{-1/2} \left\| M_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_h \chi^T \right\|$$

$$\lesssim_p s(n^{-1/2} + T^{-1/2}(\log(n \vee p \vee T))^{1/2},$$

$$n^{-1} \left\| \chi C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_h \chi^T \right\| \leq n^{-1} \left\| M_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_h \chi^T \right\| ^2 \lesssim_p s^2(n^{-1} + T^{-1}) \log(n \vee p \vee T).$$

Also, we have

$$n^{-1} \left\| C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right) \right\| = n^{-1} \left\| \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right) M_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} C_e \right\|$$

$$\lesssim \left\| C_e \right\| \max \left\| \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right\| \lesssim_p sT^{-1/2}(\log(n \vee p \vee T))^{1/2},$$

$$n^{-1} \left\| \chi C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right) \right\| = n^{-1} \left\| \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right) M_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_h \chi^T \right\|$$

$$\lesssim \left\| C_e \right\| \max \left\| \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right\| \lesssim_p s^2T^{-1/2}(\log(n \vee p \vee T)),$$

$$n^{-1} \left\| \chi C^T \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \left( \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right) \right\| \lesssim \left\| \hat{C}_g - C_g + (C_h - \hat{C}_h) \chi^T \right\| ^2 \lesssim_p s^2T^{-1} \log(n \vee p \vee T).$$

Finally, by (B.32) and Assumptions B.2 and B.3, we have

$$n^{-1} \left\| C^T_{e} \left( \hat{t}_n : \hat{C}_{\hat{h}[\hat{I}]}) \right) C_e \right\| = n^{-1} \left\| C^T_{e} \left( \hat{t}_n : \hat{C}_{\hat{h}[\hat{I}]}) \right) \left( \hat{t}_n : \hat{C}_{\hat{h}[\hat{I}]}) \right) ^{-1} \left( \hat{t}_n : \hat{C}_{\hat{h}[\hat{I}]}) \right) ^T C_e \right\|$$

$$\lesssim s n^{-2} \left\| C^T_{e} \left( \hat{t}_n : \hat{C}_{\hat{h}[\hat{I}]}) \right) \right\| ^2 \lesssim_p s(n^{-1} + T^{-1}) \log(n \vee p \vee T).$$

Hence, we obtain

$$n^{-1} \hat{C}_g \hat{M}_{(t_n; \hat{C}_{\hat{h}[\hat{I}]})} \hat{C}_g = n^{-1} C^T_{e} C_e + o_p(1).$$

The conclusion follows from (B.5) and Weyl inequalities.
Lemma 7. Under Assumptions B.1, B.2, B.3, B.4, B.5, B.6, we have
\[ \| (\tilde{\gamma}_0 : \tilde{\lambda}_h^T) - (\gamma_0 : \lambda_h^T) \| \lesssim_p s (n^{-1/2} + T^{-1/2}) (\log(n \lor p \lor T))^{1/2}. \]

Proof. It follows from (9) that
\[ (\tilde{\gamma}_0 : \tilde{\lambda}_h^T) = \left( (\tau_n : \tilde{C}_h[\tilde{I}])^T (\tau_n : \tilde{C}_h[\tilde{I}]) \right)^{-1} (\tau_n : \tilde{C}_h[\tilde{I}])^T \left( \bar{r} - \tilde{C}_g \tilde{\lambda}_g \right), \]
which implies that
\[ \left\| (\tilde{\gamma}_0 : \tilde{\lambda}_h^T) - (\gamma_0 : \lambda_h^T) \right\| \leq \left\| (\tilde{\gamma}_0 : \tilde{\lambda}_h^T) - (\gamma_0 : \lambda_h^T) \right\| + \left\| \left( \tilde{\xi} : \tilde{\chi} \right)^T \tilde{\lambda}_g - (\xi : \chi)^T \lambda_g \right\|, \]
where
\[ (\tilde{\gamma}_0 : \tilde{\lambda}_h^T) = \arg \min_{\gamma, \lambda} \left\{ \| \bar{r} - \tau_n \gamma - \tilde{C}_h \lambda \| : \lambda_j = 0, \ j \notin \tilde{I} \right\}, \]
\[ (\tilde{\xi}_j : \tilde{\chi}_j) = \arg \min_{\chi_j, \lambda_j} \left\{ \| \tilde{C}_{g_i} \chi_j - \tau_n \xi_j - \tilde{C}_h \lambda_j \| : \lambda_j = 0, \ k \notin \tilde{I} \right\}, \ j = 1, 2, \ldots, d. \]
Moreover, because
\[ M_{(\tau_n : \tilde{C}_h[\tilde{I}])^T} \bar{r} = n \gamma_0 + \tilde{C}_h \tilde{\lambda}_h - \tau_n \gamma_0 - \tilde{C}_h \tilde{\lambda}_h + (C_h - \tilde{C}_h) \tilde{\lambda}_h + C_e \lambda_g + 2 \tilde{\beta} \tilde{g} + 2 \beta \tilde{h} + \bar{u} \]
we obtain, using \( \tilde{I}_1 \subseteq \tilde{I} \), (B.1), (B.5), (B.20) - (B.23), (B.26),
\[ n^{-1/2} \left\| (\tau_n : \tilde{C}_h) \left( \tilde{\gamma}_0 - \gamma_0 : (\tilde{\lambda}_h - \lambda_h)^T \right) \right\| \leq n^{-1/2} \left\| M_{(\tau_n : \tilde{C}_h[\tilde{I}])^T} \bar{r} \right\| + n^{-1/2} \left\| (C_h - \tilde{C}_h) \tilde{\lambda}_h + C_e \lambda_g + 2 \tilde{\beta} \tilde{g} + 2 \beta \tilde{h} + \bar{u} \right\| \]
\[ \leq n^{-1/2} \left\| (\tau_n : \tilde{C}_h) \left( \gamma_0 - \gamma_0 : (\tilde{\lambda}_h - \lambda_h)^T \right) \right\| + 2 n^{-1/2} \left\| (C_h - \tilde{C}_h) \tilde{\lambda}_h + C_e \lambda_g + 2 \tilde{\beta} \tilde{g} + 2 \beta \tilde{h} + \bar{u} \right\| \]
\[ \lesssim_p s (n^{-1/2} + T^{-1/2}) (\log(n \lor p \lor T))^{1/2}. \]
Since we have
\[ n^{-1/2} \left\| (\tau_n : \tilde{C}_h) \left( \tilde{\gamma}_0 - \gamma_0 : (\tilde{\lambda}_h - \lambda_h)^T \right) \right\| \geq \phi^1_{\min} (1 + \delta) \left[ n^{-1/2} (\tau_n : \tilde{C}_h)^T (\tau_n : \tilde{C}_h) \right] \left\| (\tilde{\gamma}_0 - \gamma_0 : (\tilde{\lambda}_h - \lambda_h)^T) \right\|, \]
it follows that
\[ \left\| (\tilde{\gamma}_0 - \gamma_0 : (\tilde{\lambda}_h - \lambda_h)^T) \right\| \lesssim_p s (n^{-1/2} + T^{-1/2}) (\log(n \lor p \lor T))^{1/2}. \]
Similarly, we can obtain
\[ \left\| (\tilde{\xi} - \xi : \tilde{\chi} - \chi) \right\| \lesssim_p s (n^{-1/2} + T^{-1/2}) (\log(n \lor p \lor T))^{1/2}. \]
Therefore, using this, as well as Assumption B.1 and Theorem 1, we obtain
\[ \left\| (\tilde{\xi} : \tilde{\chi})^T \tilde{\lambda}_g - (\xi : \chi)^T \lambda_g \right\| \leq \left\| (\tilde{\xi} - \xi : \tilde{\chi} - \chi) \right\| \left\| \tilde{\lambda}_g \right\| + \left\| (\xi : \chi) \left\| \tilde{\lambda}_g - \lambda_g \right\| \right\| \lesssim_p s (n^{-1/2} + T^{-1/2}) (\log(n \lor p \lor T))^{1/2}. \]
This concludes the proof.\[\square\]
References


